



# Single Supply, Rail-to-Rail Low Power, FET-Input Op Amp

## AD824

### FEATURES

Single Supply Operation: 3 V to 30 V  
Very Low Input Bias Current: 2 pA  
Wide Input Voltage Range  
Rail-to-Rail Output Swing  
Low Supply Current: 500  $\mu$ A/Amp  
Wide Bandwidth: 2 MHz  
Slew Rate: 2 V/ $\mu$ s  
No Phase Reversal

### APPLICATIONS

Photo Diode Preamplifier  
Battery Powered Instrumentation  
Power Supply Control and Protection  
Medical Instrumentation  
Remote Sensors  
Low Voltage Strain Gage Amplifiers  
DAC Output Amplifier

### GENERAL DESCRIPTION

The AD824 is a quad, FET input, single supply amplifier, featuring rail-to-rail outputs. The combination of FET inputs and rail-to-rail outputs makes the AD824 useful in a wide variety of low voltage applications where low input current is a primary consideration.

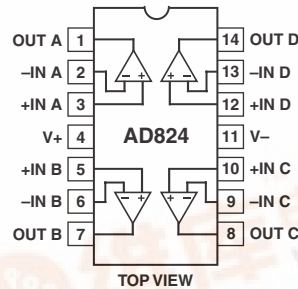
The AD824 is guaranteed to operate from a 3 V single supply up to  $\pm 15$  V dual supplies.

Fabricated on ADI's complementary bipolar process, the AD824 has a unique input stage that allows the input voltage to safely extend beyond the negative supply and to the positive supply without any phase inversion or latchup. The output voltage swings to within 15 mV of the supplies. Capacitive loads to 350 pF can be handled without oscillation.

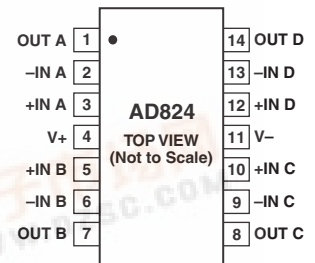
The FET input combined with laser trimming provides an input that has extremely low bias currents with guaranteed offsets below 300  $\mu$ V. This enables high accuracy designs even with high source impedances. Precision is combined with low noise, making the AD824 ideal for use in battery powered medical equipment.

### PIN CONFIGURATIONS

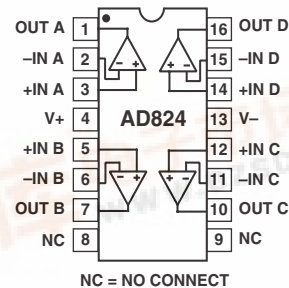
14-Lead Epoxy DIP  
(N Suffix)



14-Lead Epoxy SO  
(R Suffix)



16-Lead Epoxy SO  
(R Suffix)



Applications for the AD824 include portable medical equipment, photo diode preamplifiers and high impedance transducer amplifiers.

The ability of the output to swing rail-to-rail enables designers to build multistage filters in single supply systems and maintain high signal-to-noise ratios.

The AD824 is specified over the extended industrial ( $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ) temperature range and is available in 14-pin DIP and narrow 14-lead and 16-lead SO packages.

REV. B

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# AD824—SPECIFICATIONS

## ELECTRICAL SPECIFICATIONS (@ $V_S = 5.0\text{ V}$ , $V_{CM} = 0\text{ V}$ , $V_{OUT} = 0.2\text{ V}$ , $T_A = 25^\circ\text{C}$ unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
<b>INPUT CHARACTERISTICS</b>						
Offset Voltage AD824A	$V_{OS}$	$T_{MIN}$ to $T_{MAX}$		0.1	1.0	mV
Input Bias Current	$I_B$	$T_{MIN}$ to $T_{MAX}$		2	12	pA
Input Offset Current	$I_{OS}$	$T_{MIN}$ to $T_{MAX}$		300	4000	pA
Input Voltage Range		$T_{MIN}$ to $T_{MAX}$		2	10	pA
Common-Mode Rejection Ratio	CMRR	$T_{MIN}$ to $T_{MAX}$		300		pA
		$V_{CM} = 0\text{ V}$ to $2\text{ V}$	-0.2		3.0	V
		$V_{CM} = 0\text{ V}$ to $3\text{ V}$	66	80		dB
		$T_{MIN}$ to $T_{MAX}$	60	74		dB
Input Impedance						dB
Large Signal Voltage Gain	$A_{VO}$	$V_O = 0.2\text{ V}$ to $4.0\text{ V}$		$10^{13}  3.3$		$\Omega  \text{pF}$
		$R_L = 2\text{ k}\Omega$	20	40		V/mV
		$R_L = 10\text{ k}\Omega$	50	100		V/mV
		$R_L = 100\text{ k}\Omega$	250	1000		V/mV
		$T_{MIN}$ to $T_{MAX}$ , $R_L = 100\text{ k}\Omega$	180	400		V/mV
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$			2		$\mu\text{V}/^\circ\text{C}$
<b>OUTPUT CHARACTERISTICS</b>						
Output Voltage High	$V_{OH}$	$I_{SOURCE} = 20\text{ }\mu\text{A}$	4.975	4.988		V
		$T_{MIN}$ to $T_{MAX}$	4.97	4.985		V
		$I_{SOURCE} = 2.5\text{ mA}$	4.80	4.85		V
		$T_{MIN}$ to $T_{MAX}$	4.75	4.82		V
Output Voltage Low	$V_{OL}$	$I_{SINK} = 20\text{ }\mu\text{A}$		15	25	mV
		$T_{MIN}$ to $T_{MAX}$		20	30	mV
		$I_{SINK} = 2.5\text{ mA}$		120	150	mV
		$T_{MIN}$ to $T_{MAX}$		140	200	mV
Short Circuit Limit	$I_{SC}$	Sink/Source		$\pm 12$		mA
		$T_{MIN}$ to $T_{MAX}$		$\pm 10$		mA
Open-Loop Impedance	$Z_{OUT}$	$f = 1\text{ MHz}$ , $A_V = 1$		100		$\Omega$
<b>POWER SUPPLY</b>						
Power Supply Rejection Ratio	PSRR	$V_S = 2.7\text{ V}$ to $12\text{ V}$	70	80		dB
		$T_{MIN}$ to $T_{MAX}$	66			dB
Supply Current/Amplifier	$I_{SY}$	$T_{MIN}$ to $T_{MAX}$		500	600	$\mu\text{A}$
<b>DYNAMIC PERFORMANCE</b>						
Slew Rate	SR	$R_L = 10\text{ k}\Omega$ , $A_V = 1$		2		V/ $\mu\text{s}$
Full-Power Bandwidth	$BW_P$	1% Distortion, $V_O = 4\text{ V p-p}$		150		kHz
Settling Time	$t_s$	$V_{OUT} = 0.2\text{ V}$ to $4.5\text{ V}$ , to 0.01%		2.5		$\mu\text{s}$
Gain Bandwidth Product	GBP			2		MHz
Phase Margin	$\phi_o$	No Load		50		Degrees
Channel Separation	CS	$f = 1\text{ kHz}$ , $R_L = 2\text{ k}\Omega$		-123		dB
<b>NOISE PERFORMANCE</b>						
Voltage Noise	$e_n\text{ p-p}$	0.1 Hz to 10 Hz		2		$\mu\text{V p-p}$
Voltage Noise Density	$e_n$	$f = 1\text{ kHz}$		16		$\text{nV}/\sqrt{\text{Hz}}$
Current Noise Density	$i_n$	$f = 1\text{ kHz}$		0.8		$\text{fA}/\sqrt{\text{Hz}}$
Total Harmonic Distortion	THD	$f = 10\text{ kHz}$ , $R_L = 0$ , $A_V = +1$		0.005		%

**ELECTRICAL SPECIFICATIONS** (@  $V_S = \pm 15.0\text{ V}$ ,  $V_{OUT} = 0\text{ V}$ ,  $T_A = 25^\circ\text{C}$  unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
INPUT CHARACTERISTICS						
Offset Voltage AD824A	V <sub>OS</sub>			0.5	2.5	mV
Input Bias Current	I <sub>B</sub>	T <sub>MIN</sub> to T <sub>MAX</sub>		0.6	4.0	mV
		V <sub>CM</sub> = 0 V		4	35	pA
Input Offset Current	I <sub>B</sub> I <sub>OS</sub>	T <sub>MIN</sub> to T <sub>MAX</sub>		500	4000	pA
		V <sub>CM</sub> = −10 V		25		pA
				3	20	pA
Input Voltage Range		T <sub>MIN</sub> to T <sub>MAX</sub>		500		pA
Common-Mode Rejection Ratio	CMRR		−15		13	V
		V <sub>CM</sub> = −15 V to 13 V	70	80		dB
Input Impedance		T <sub>MIN</sub> to T <sub>MAX</sub>		66		dB
Large Signal Voltage Gain	A <sub>VO</sub>			10 <sup>13</sup>   3.3		Ω  pF
		V <sub>O</sub> = −10 V to +10 V;				
		R <sub>L</sub> = 2 kΩ	12	50		V/mV
		R <sub>L</sub> = 10 kΩ	50	200		V/mV
		R <sub>L</sub> = 100 kΩ	300	2000		V/mV
Offset Voltage Drift	ΔV <sub>OS</sub> /ΔT	T <sub>MIN</sub> to T <sub>MAX</sub> , R <sub>L</sub> = 100 kΩ	200	1000		V/mV
				2		μV/°C
OUTPUT CHARACTERISTICS						
Output Voltage High	V <sub>OH</sub>	I <sub>SOURCE</sub> = 20 μA	14.975	14.988		V
Output Voltage Low	V <sub>OL</sub>	T <sub>MIN</sub> to T <sub>MAX</sub>	14.970	14.985		V
		I <sub>SOURCE</sub> = 2.5 mA	14.80	14.85		V
		T <sub>MIN</sub> to T <sub>MAX</sub>	14.75	14.82		V
		I <sub>SINK</sub> = 20 μA		−14.985	−14.975	V
		T <sub>MIN</sub> to T <sub>MAX</sub>		−14.98	−14.97	V
		I <sub>SINK</sub> = 2.5 mA		−14.88	−14.85	V
		T <sub>MIN</sub> to T <sub>MAX</sub>		−14.86	−14.8	V
		Sink/Source, T <sub>MIN</sub> to T <sub>MAX</sub>				V
Short Circuit Limit	I <sub>SC</sub>	Sink/Source, T <sub>MIN</sub> to T <sub>MAX</sub>	±8	±20		mA
Open-Loop Impedance	Z <sub>OUT</sub>	f = 1 MHz, A <sub>V</sub> = 1		100		Ω
POWER SUPPLY						
Power Supply Rejection Ratio	PSRR	V <sub>S</sub> = 2.7 V to 15 V	70	80		dB
Supply Current/Amplifier	I <sub>SY</sub>	T <sub>MIN</sub> to T <sub>MAX</sub>	68			dB
		V <sub>O</sub> = 0 V		560	625	μA
		T <sub>MIN</sub> to T <sub>MAX</sub>			675	μA
DYNAMIC PERFORMANCE						
Slew Rate	SR	R <sub>L</sub> = 10 kΩ, A <sub>V</sub> = 1		2		V/μs
Full-Power Bandwidth	BW <sub>p</sub>	1% Distortion, V <sub>O</sub> = 20 V p-p		33		kHz
Settling Time	t <sub>s</sub>	V <sub>OUT</sub> = 0 V to 10 V, to 0.01%		6		μs
Gain Bandwidth Product	GBP			2		MHz
Phase Margin	φ <sub>o</sub>			50		Degrees
Channel Separation	CS	f = 1 kHz, R <sub>L</sub> =2 kΩ		−123		dB
NOISE PERFORMANCE						
Voltage Noise	e <sub>n</sub> p-p	0.1 Hz to 10 Hz		2		μV p-p
Voltage Noise Density	e <sub>n</sub>	f = 1 kHz		16		nV/√Hz
Current Noise Density	i <sub>n</sub>	f = 1 kHz		1.1		fA/√Hz
Total Harmonic Distortion	THD	f =10 kHz, V <sub>O</sub> = 3 V rms, R <sub>L</sub> = 10 kΩ		0.005		%

# AD824—SPECIFICATIONS

## ELECTRICAL SPECIFICATIONS (@ $V_S = 3.0\text{ V}$ , $V_{CM} = 0\text{ V}$ , $V_{OUT} = 0.2\text{ V}$ , $T_A = 25^\circ\text{C}$ unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
<b>INPUT CHARACTERISTICS</b>						
Offset Voltage AD824A -3 V	$V_{OS}$	$T_{MIN}$ to $T_{MAX}$		0.2	1.0	mV
Input Bias Current	$I_B$	$T_{MIN}$ to $T_{MAX}$		2	12	pA
Input Offset Current	$I_{OS}$	$T_{MIN}$ to $T_{MAX}$		250	4000	pA
Input Voltage Range		$T_{MIN}$ to $T_{MAX}$		2	10	pA
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0\text{ V}$ to $1\text{ V}$ $T_{MIN}$ to $T_{MAX}$	0 58 56	74	1	V dB dB
Input Impedance				$10^{13}  3.3$		$\Omega  \text{pF}$
Large Signal Voltage Gain	$A_{VO}$	$V_O = 0.2\text{ V}$ to $2.0\text{ V}$ $R_L = 2\text{ k}\Omega$ $R_L = 10\text{ k}\Omega$ $R_L = 100\text{ k}\Omega$ $T_{MIN}$ to $T_{MAX}$ , $R_L = 100\text{ k}\Omega$	10 30 180 90	20 65 500 250		V/mV V/mV V/mV V/mV
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$			2		$\mu\text{V}/^\circ\text{C}$
<b>OUTPUT CHARACTERISTICS</b>						
Output Voltage High	$V_{OH}$	$I_{SOURCE} = 20\text{ }\mu\text{A}$ $T_{MIN}$ to $T_{MAX}$ $I_{SOURCE} = 2.5\text{ mA}$ $T_{MIN}$ to $T_{MAX}$	2.975 2.97 2.8 2.75	2.988 2.985 2.85 2.82		V V V V
Output Voltage Low	$V_{OL}$	$I_{SINK} = 20\text{ }\mu\text{A}$ $T_{MIN}$ to $T_{MAX}$ $I_{SINK} = 2.5\text{ mA}$ $T_{MIN}$ to $T_{MAX}$		15 20 120 140	25 30 150 200	mV mV mV mV
Short Circuit Limit	$I_{SC}$	Sink/Source		$\pm 8$		mA
Open-Loop Impedance	$I_{SC}$ $Z_{OUT}$	Sink/Source, $T_{MIN}$ to $T_{MAX}$ $f = 1\text{ MHz}$ , $A_V = 1$		$\pm 6$ 100		mA $\Omega$
<b>POWER SUPPLY</b>						
Power Supply Rejection Ratio	PSRR	$V_S = 2.7\text{ V}$ to $12\text{ V}$ , $T_{MIN}$ to $T_{MAX}$	70 66			dB dB
Supply Current/Amplifier	$I_{SY}$	$V_O = 0.2\text{ V}$ , $T_{MIN}$ to $T_{MAX}$		500	600	$\mu\text{A}$
<b>DYNAMIC PERFORMANCE</b>						
Slew Rate	SR	$R_L = 10\text{ k}\Omega$ , $A_V = 1$		2		V/ $\mu\text{s}$
Full-Power Bandwidth	$BW_P$	1% Distortion, $V_O = 2\text{ V p-p}$		300		kHz
Settling Time	$t_S$	$V_{OUT} = 0.2\text{ V}$ to $2.5\text{ V}$ , to 0.01%		2		$\mu\text{s}$
Gain Bandwidth Product	GBP			2		MHz
Phase Margin	$\phi_o$			50		Degrees
Channel Separation	CS	$f = 1\text{ kHz}$ , $R_L = 2\text{ k}\Omega$		-123		dB
<b>NOISE PERFORMANCE</b>						
Voltage Noise	$e_n\text{ p-p}$	0.1 Hz to 10 Hz		2		$\mu\text{V p-p}$
Voltage Noise Density	$e_n$	$f = 1\text{ kHz}$		16		$\text{nV}/\sqrt{\text{Hz}}$
Current Noise Density	$i_n$			0.8		$\text{fA}/\sqrt{\text{Hz}}$
Total Harmonic Distortion	THD	$f = 10\text{ kHz}$ , $R_L = 0$ , $A_V = +1$		0.01		%

# **WAFER TEST LIMITS** (@ $V_S = 5.0\text{ V}$ , $V_{CM} = 0\text{ V}$ , $T_A = 25^\circ\text{C}$ unless otherwise noted)

Parameter	Symbol	Conditions	Limit	Unit
Offset Voltage	$V_{OS}$		1.0	mV max
Input Bias Current	$I_B$		12	pA max
Input Offset Current	$I_{OS}$		20	pA
Input Voltage Range	$V_{CM}$		-0.2 to 3.0	V min
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0\text{ V to } 2\text{ V}$	66	dB min
Power Supply Rejection Ratio	PSRR	$V = +2.7\text{ V to } +12\text{ V}$	70	$\mu\text{V/V}$
Large Signal Voltage Gain	$A_{VO}$	$R_L = 2\text{ k}\Omega$	15	V/mV min
Output Voltage High	$V_{OH}$	$I_{SOURCE} = 20\text{ }\mu\text{A}$	4.975	V min
Output Voltage Low	$V_{OL}$	$I_{SINK} = 20\text{ }\mu\text{A}$	25	mV max
Supply Current/Amplifier	$I_{SY}$	$V_O = 0\text{ V}$ , $R_L = \infty$	600	$\mu\text{A max}$

## **NOTE**

Electrical tests and wafer probe to the limits shown. Due to variations in assembly methods and normal yield loss, yield after packaging is not guaranteed for standard product dice. Consult factory to negotiate specifications based on dice lot qualifications through sample lot assembly and testing.

## **ABSOLUTE MAXIMUM RATINGS<sup>1</sup>**

Supply Voltage	$\pm 18\text{ V}$
Input Voltage	$-V_S - 0.2\text{ V to } +V_S$
Differential Input Voltage	$\pm 30\text{ V}$
Output Short Circuit Duration to GND	Indefinite
Storage Temperature Range	
N, R Package	$-65^\circ\text{C to } +150^\circ\text{C}$
Operating Temperature Range	
AD824A	$-40^\circ\text{C to } +85^\circ\text{C}$
Junction Temperature Range	
N, R Package	$-65^\circ\text{C to } +150^\circ\text{C}$
Lead Temperature Range (Soldering 60 sec)	$300^\circ\text{C}$

Package Type	$\theta_{JA}^2$	$\theta_{JC}$	Units
14-Pin Plastic DIP (N)	76	33	$^\circ\text{C/W}$
14-Pin SOIC (R)	120	36	$^\circ\text{C/W}$
16-Pin SOIC (R)	92	27	$^\circ\text{C/W}$

## **NOTES**

<sup>1</sup> Absolute maximum ratings apply to packaged parts unless otherwise noted.

<sup>2</sup>  $\theta_{JA}$  is specified for the worst case conditions, i.e.,  $\theta_{JA}$  is specified for device in socket for P-DIP packages;  $\theta_{JA}$  is specified for device soldered in circuit board for SOIC package.

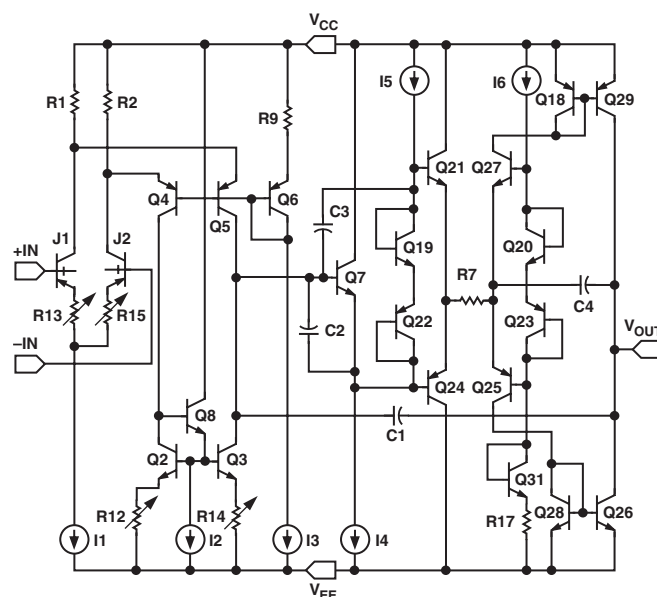


Figure 1. Simplified Schematic of 1/4 AD824

## **ORDERING GUIDE**

Model	Temperature Range	Package Description	Package Option
AD824AN*	$-40^\circ\text{C to } +85^\circ\text{C}$	14-Pin Plastic DIP	N-14
AD824AR	$-40^\circ\text{C to } +85^\circ\text{C}$	14-Pin SOIC	R-14
AD824AR-3V	$-40^\circ\text{C to } +85^\circ\text{C}$	14-Pin SOIC	R-14
AD824AR-14	$-40^\circ\text{C to } +85^\circ\text{C}$	14-Pin SOIC	R-14
AD824AR-14-3V	$-40^\circ\text{C to } +85^\circ\text{C}$	14-Pin SOIC	R-14
AD824AR-16	$-40^\circ\text{C to } +85^\circ\text{C}$	16-Pin SOIC	R-16

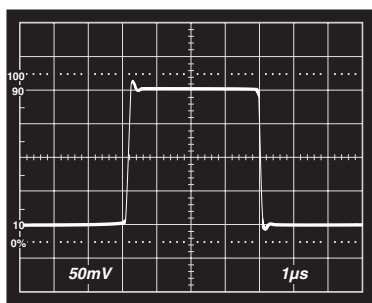
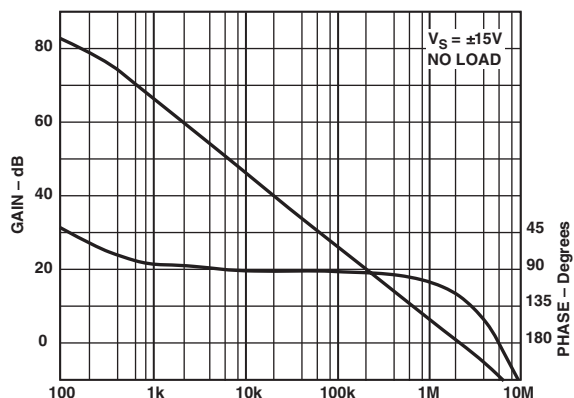
\*Not for new designs. Obsolete April 2002.

## **CAUTION**

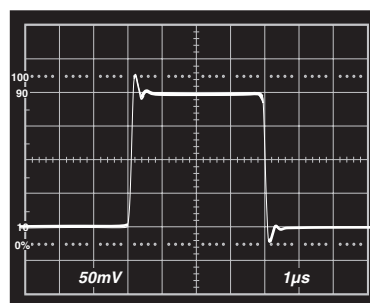
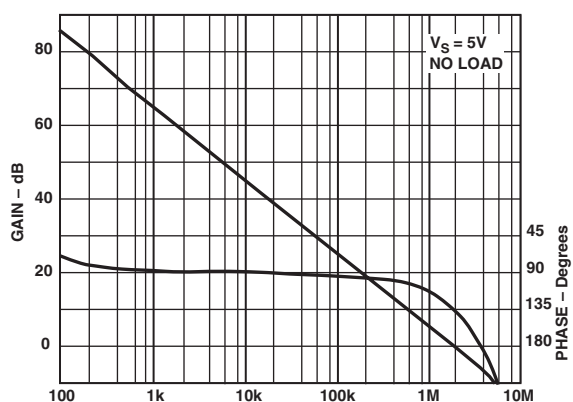
ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD824 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



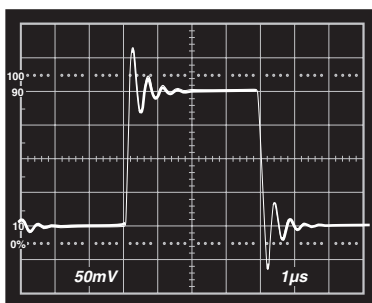
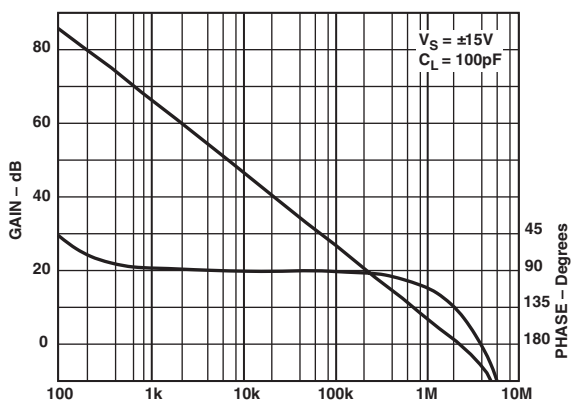
# AD824—Typical Performance Characteristics



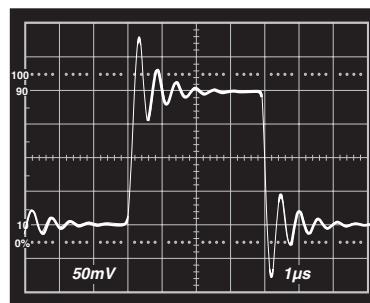
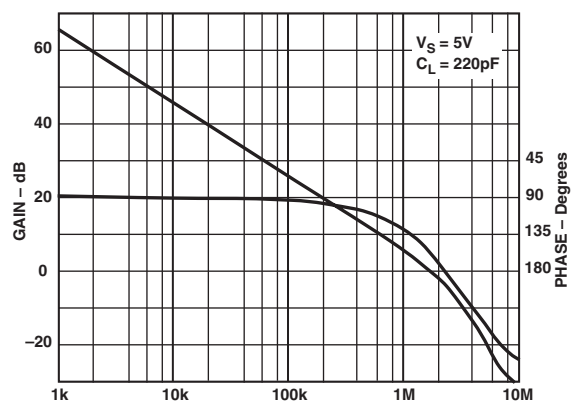
TPC 1. Open-Loop Gain/Phase and Small Signal Response,  $V_S = \pm 15V$ , No Load



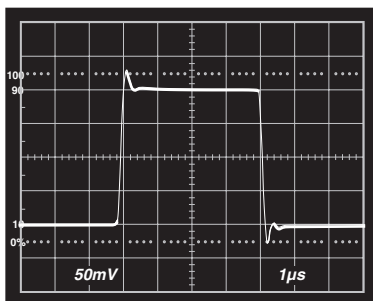
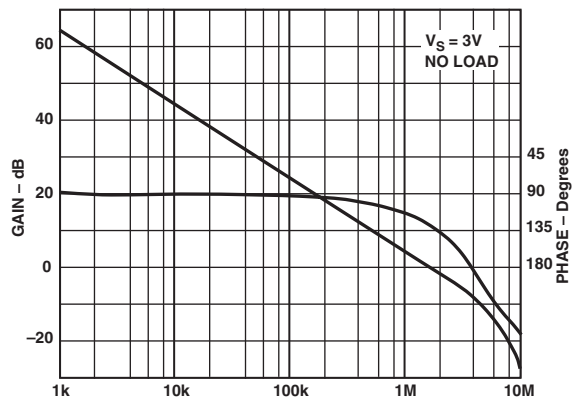
TPC 3. Open-Loop Gain/Phase and Small Signal Response,  $V_S = 5V$ , No Load



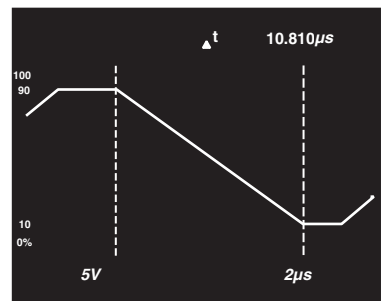
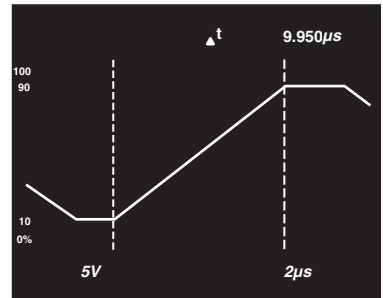
TPC 2. Open-Loop Gain/Phase and Small Signal Response,  $V_S = \pm 15V$ ,  $C_L = 100pF$



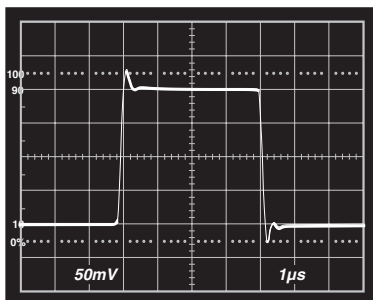
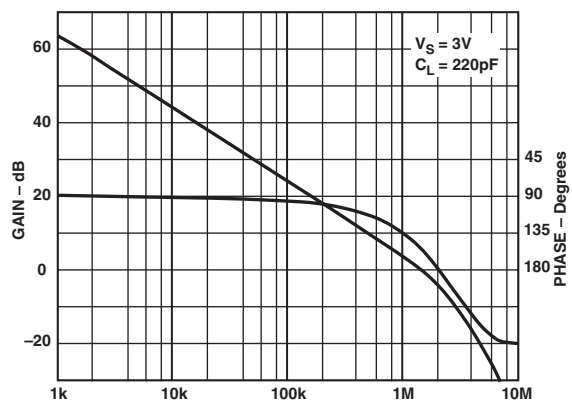
TPC 4. Open-Loop Gain/Phase and Small Signal Response,  $V_S = 5V$ ,  $C_L = 220pF$



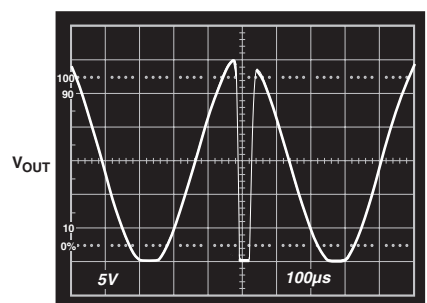
TPC 5. Open-Loop Gain/Phase and Small Signal Response,  $V_S = 3V$ , No Load



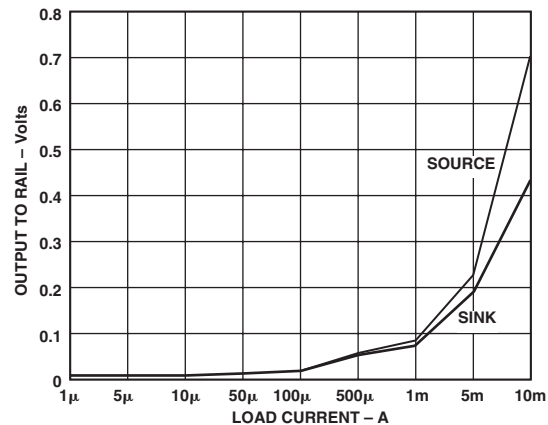
TPC 7. Slew Rate,  $R_L = 10k$



TPC 6. Open-Loop Gain/Phase and Small Signal Response,  $V_S = 3V$ ,  $C_L = 220pF$

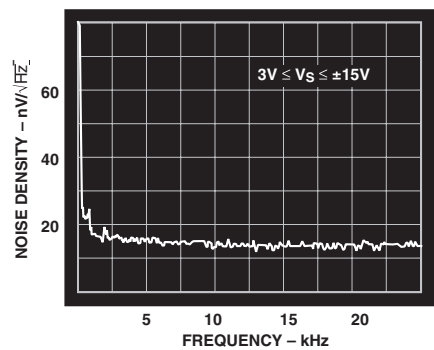


TPC 8. Phase Reversal with Inputs Exceeding Supply by 1 V

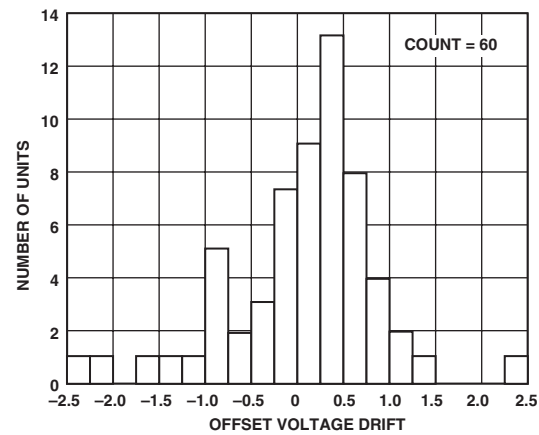


TPC 9. Output Voltage to Supply Rail vs. Sink and Source Load Currents

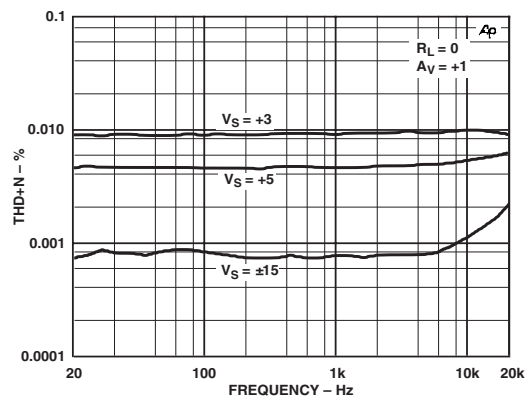
# AD824—TYPICAL PERFORMANCE CHARACTERISTICS



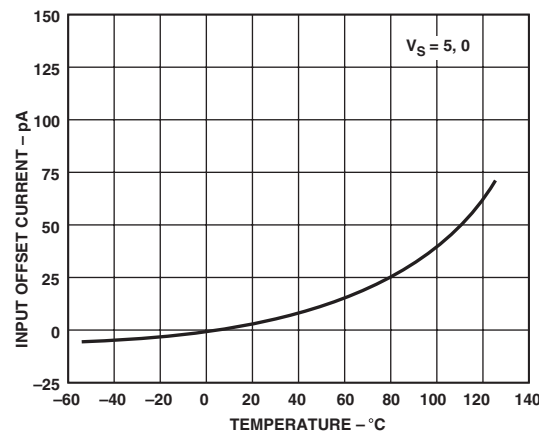
TPC 10. Voltage Noise Density



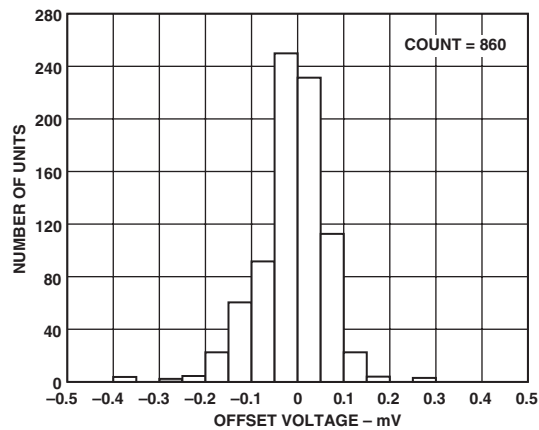
TPC 13. TC  $V_{OS}$  Distribution,  $-55^{\circ}C$  to  $+125^{\circ}C$ ,  $V_S = 5, 0$



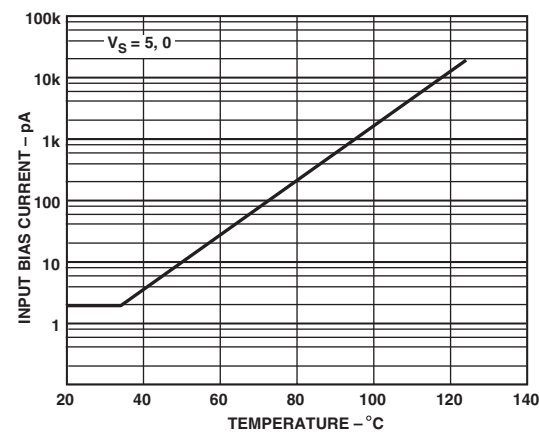
TPC 11. Total Harmonic Distortion



TPC 14. Input Offset Current vs. Temperature

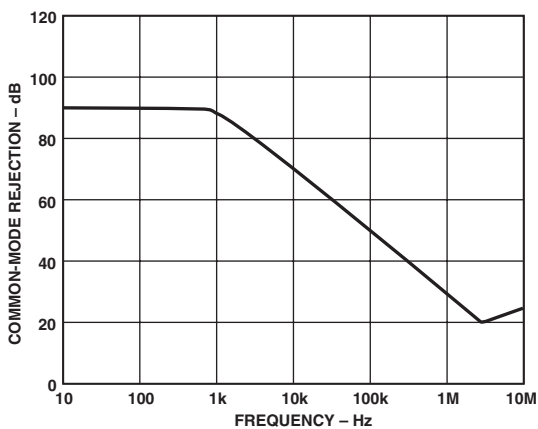


TPC 12. Input Offset Distribution,  $V_S = 5, 0$

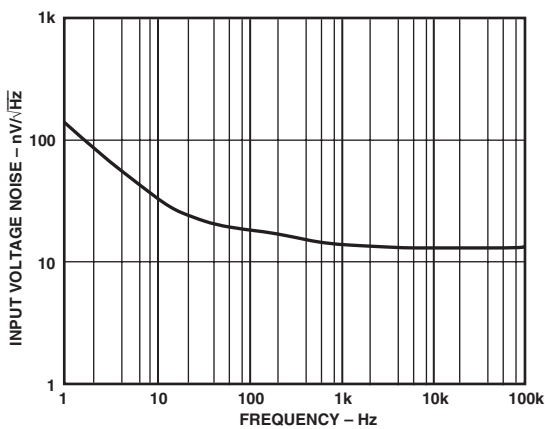


TPC 15. Input Bias Current vs. Temperature

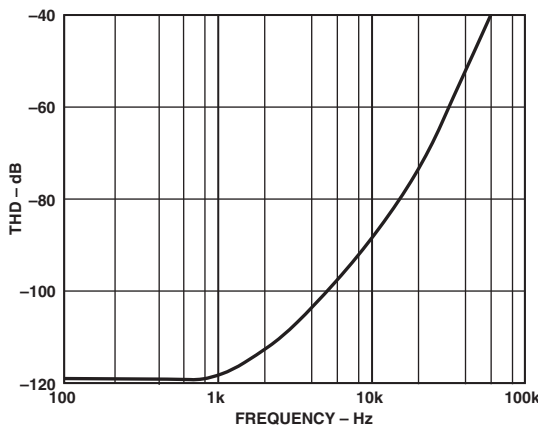




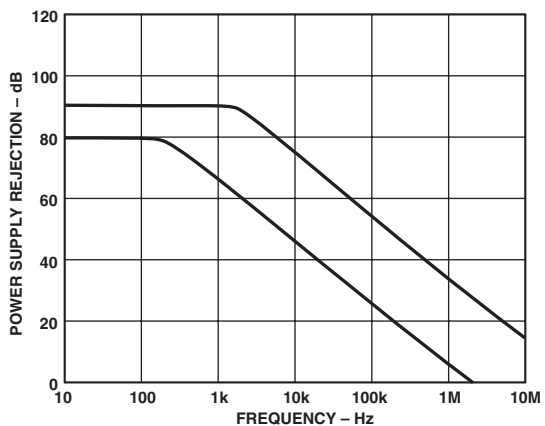
TPC 16. Common-Mode Rejection vs. Frequency



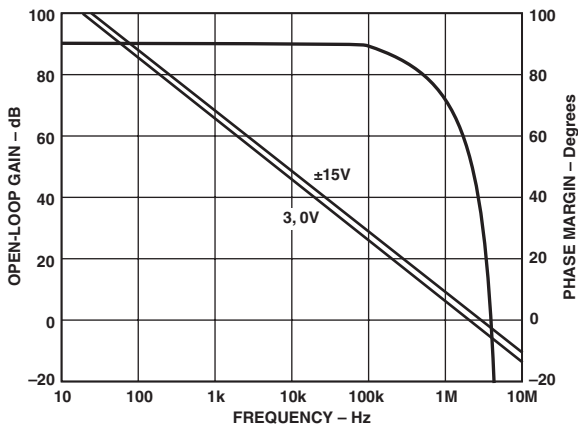
TPC 19. Input Voltage Noise Spectral Density vs. Frequency



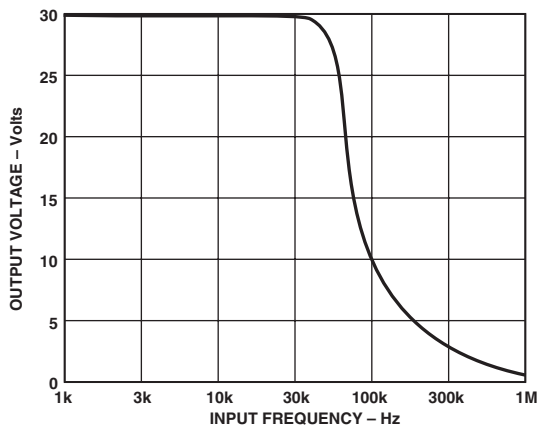
TPC 17. THD vs. Frequency, 3 V rms



TPC 20. Power Supply Rejection vs. Frequency

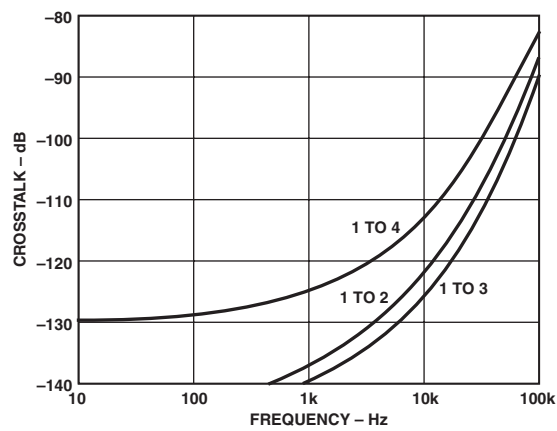


TPC 18. Open-Loop Gain and Phase vs. Frequency

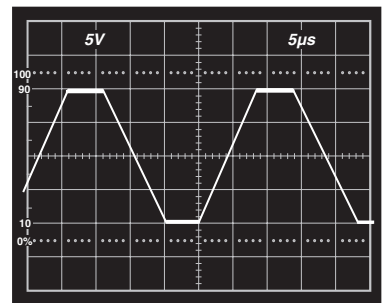


TPC 21. Large Signal Frequency Response

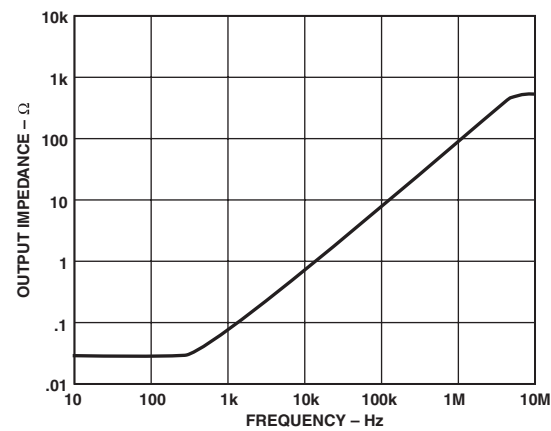
AD824



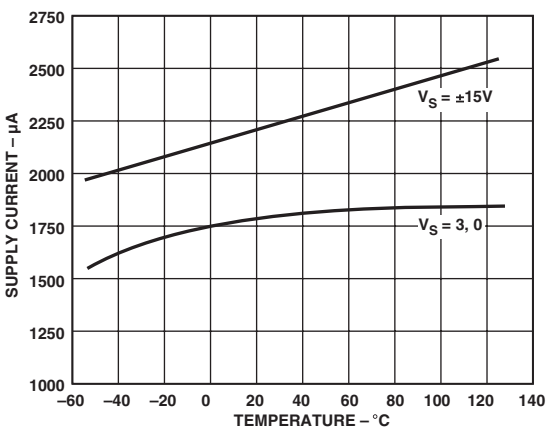
TPC 22. Crosstalk vs. Frequency



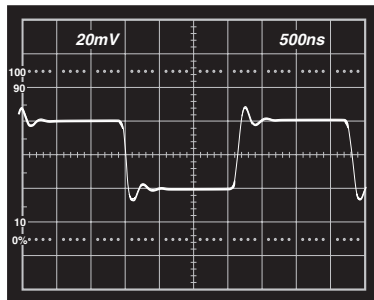
TPC 25. Large Signal Response



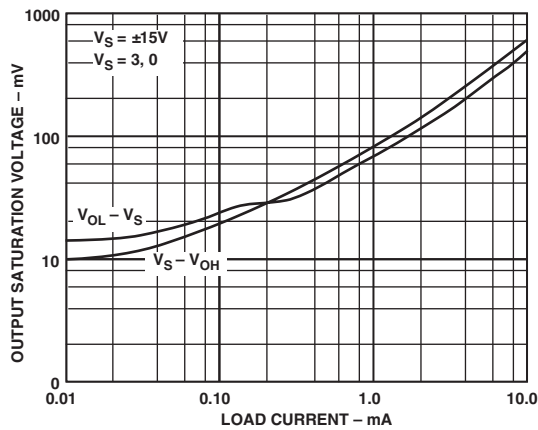
TPC 23. Output Impedance vs. Frequency, Gain = +1



TPC 26. Supply Current vs. Temperature



TPC 24. Small Signal Response, Unity Gain Follower, 10k||100 pF Load



TPC 27. Output Saturation Voltage

## APPLICATION NOTES

### INPUT CHARACTERISTICS

In the AD824, n-channel JFETs are used to provide a low offset, low noise, high impedance input stage. Minimum input common-mode voltage extends from 0.2 V below  $-V_S$  to 1 V less than  $+V_S$ . Driving the input voltage closer to the positive rail will cause a loss of amplifier bandwidth.

The AD824 does not exhibit phase reversal for input voltages up to and including  $+V_S$ . Figure 2a shows the response of an AD824 voltage follower to a 0 V to 5 V ( $+V_S$ ) square wave input. The input and output are superimposed. The output tracks the input up to  $+V_S$  without phase reversal. The reduced bandwidth above a 4 V input causes the rounding of the output wave form. For input voltages greater than  $+V_S$ , a resistor in series with the AD824's noninverting input will prevent phase reversal at the expense of greater input voltage noise. This is illustrated in Figure 2b.

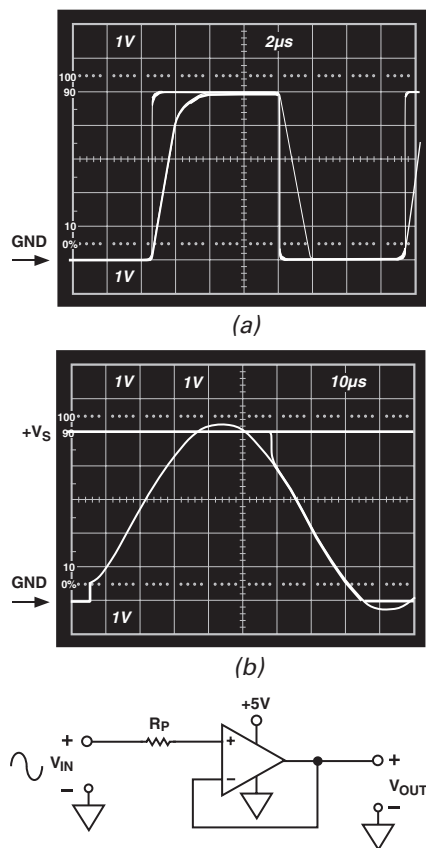


Figure 2. (a) Response with  $R_P = 0$ ;  $V_{IN}$  from 0 to  $+V_S$   
(b)  $V_{IN} = 0$  to  $+V_S + 200$  mV  
 $V_{OUT} = 0$  to  $+V_S$   
 $R_P = 49.9$  k $\Omega$

Since the input stage uses n-channel JFETs, input current during normal operation is positive; the current flows out from the input terminals. If the input voltage is driven more positive than  $+V_S - 0.4$  V, the input current will reverse direction as internal device junctions become forward biased. This is illustrated in TPC 8.

A current-limiting resistor should be used in series with the input of the AD824 if there is a possibility of the input voltage exceeding the positive supply by more than 300 mV or if an input voltage will be applied to the AD824 when  $\pm V_S = 0$ . The amplifier will be damaged if left in that condition for more than 10 seconds. A 1 k $\Omega$  resistor allows the amplifier to withstand up to 10 V of continuous overvoltage and increases the input voltage noise by a negligible amount.

Input voltages less than  $-V_S$  are a completely different story. The amplifier can safely withstand input voltages 20 V below the minus supply voltage as long as the total voltage from the positive supply to the input terminal is less than 36 V. In addition, the input stage typically maintains picoamp level input currents across that input voltage range.

### OUTPUT CHARACTERISTICS

The AD824's unique bipolar rail-to-rail output stage swings within 15 mV of the positive and negative supply voltages. The AD824's approximate output saturation resistance is 100  $\Omega$  for both sourcing and sinking. This can be used to estimate output saturation voltage when driving heavier current loads. For instance, the saturation voltage will be 0.5 V from either supply with a 5 mA current load.

For load resistances over 20 k $\Omega$ , the AD824's input error voltage is virtually unchanged until the output voltage is driven to 180 mV of either supply.

If the AD824's output is overdriven so as to saturate either of the output devices, the amplifier will recover within 2  $\mu$ s of its input returning to the amplifier's linear operating region.

Direct capacitive loads will interact with the amplifier's effective output impedance to form an additional pole in the amplifier's feedback loop, which can cause excessive peaking on the pulse response or loss of stability. Worst case is when the amplifier is used as a unity gain follower. TPC 4 and 6 show the AD824's pulse response as a unity gain follower driving 220 pF. Configurations with less loop gain, and as a result less loop bandwidth, will be much less sensitive to capacitance load effects. Noise gain is the inverse of the feedback attenuation factor provided by the feedback network in use.

Figure 3 shows a method for extending capacitance load drive capability for a unity gain follower. With these component values, the circuit will drive 5,000 pF with a 10% overshoot.

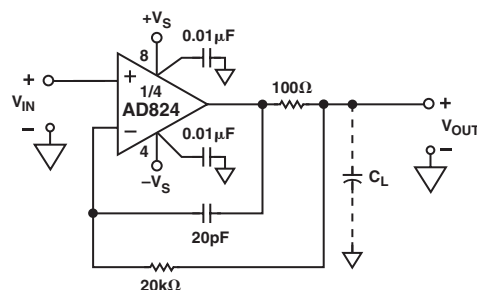


Figure 3. Extending Unity Gain Follower Capacitive Load Capability Beyond 350 pF

**Figure 5b. A Single Supply Programmable Instrumentation Amplifier**

## 3 Volt, Single Supply Stereo Headphone Driver

The AD824 exhibits good current drive and THD+N performance, even at 3 V single supplies. At 1 kHz, total harmonic distortion plus noise (THD+N) equals  $-62$  dB (0.079%) for a 300 mV p-p output signal. This is comparable to other single supply op amps that consume more power and cannot run on 3 V power supplies.

In Figure 6, each channel's input signal is coupled via a  $1\ \mu\text{F}$  Mylar capacitor. Resistor dividers set the dc voltage at the noninverting inputs so that the output voltage is midway between the power supplies (1.5 V). The gain is 1.5. Each half of the AD824 can then be used to drive a headphone channel. A 5 Hz high-pass filter is realized by the  $500\ \mu\text{F}$  capacitors and the headphones, which can be modeled as 32 ohm load resistors to ground. This ensures that all signals in the audio frequency range (20 Hz–20 kHz) are delivered to the headphones.

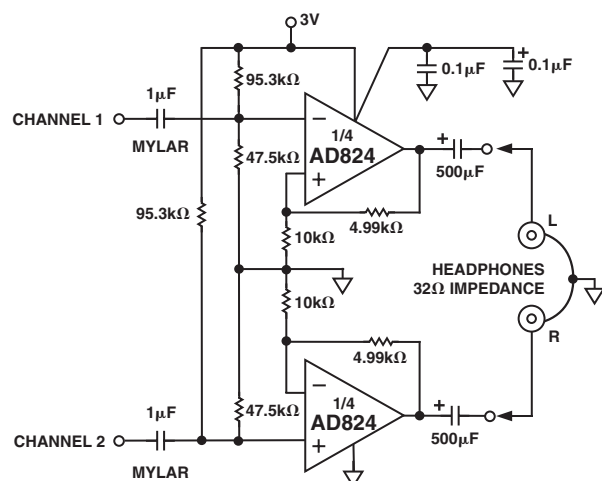


Figure 6. 3 Volt Single Supply Stereo Headphone Driver

## Low Dropout Bipolar Bridge Driver

The AD824 can be used for driving a 350 ohm Wheatstone bridge. Figure 7 shows one half of the AD824 being used to buffer the AD589—a 1.235 V low power reference. The output

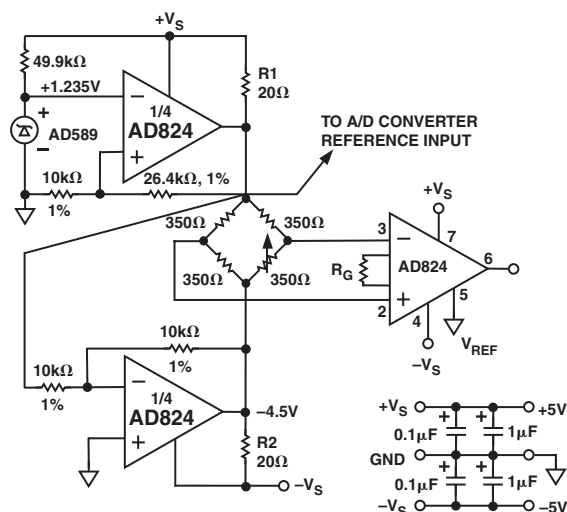


Figure 7. Low Dropout Bipolar Bridge Driver

of 4.5 V can be used to drive an A/D converter front end. The other half of the AD824 is configured as a unity-gain inverter and generates the other bridge input of  $-4.5$  V. Resistors R1 and R2 provide a constant current for bridge excitation. The AD620 low power instrumentation amplifier is used to condition the differential output voltage of the bridge. The gain of the AD620 is programmed using an external resistor  $R_G$  and determined by:

$$G = \frac{49.4\ \text{k}\Omega}{R_G} + 1$$

## A 3.3 V/5 V Precision Sample-and-Hold Amplifier

In battery-powered applications, low supply voltage operational amplifiers are required for low power consumption. Also, low supply voltage applications limit the signal range in precision analog circuitry. Circuits like the sample-and-hold circuit shown in Figure 8, illustrate techniques for designing precision analog circuitry in low supply voltage applications. To maintain high signal-to-noise ratios (SNRs) in a low supply voltage application requires the use of rail-to-rail, input/output operational amplifiers. This design highlights the ability of the AD824 to operate rail-to-rail from a single 3 V/5 V supply, with the advantages of high input impedance. The AD824, a quad JFET-input op amp, is well suited to S/H circuits due to its low input bias currents (3 pA, typical) and high input impedances ( $3 \times 10^{13}\ \Omega$ , typical). The AD824 also exhibits very low supply currents so the total supply current in this circuit is less than 2.5 mA.

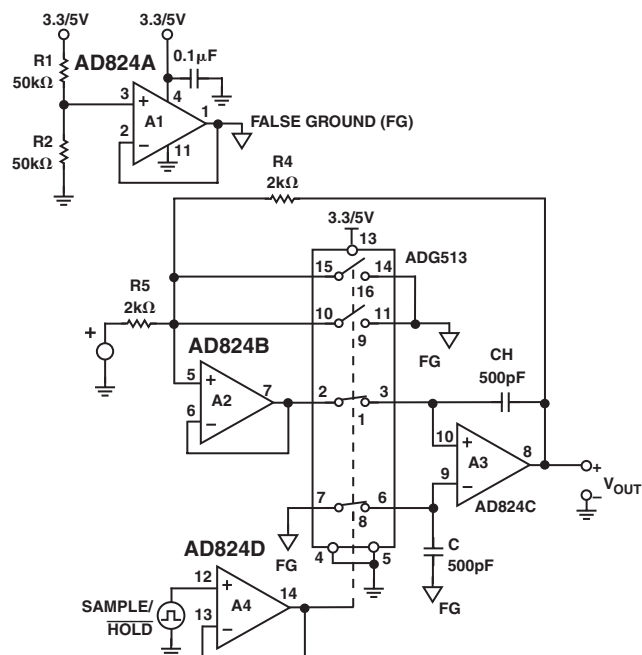


Figure 8. 3.3 V/5.5 V Precision Sample and Hold

In many single supply applications, the use of a false ground generator is required. In this circuit, R1 and R2 divide the supply voltage symmetrically, creating the false ground voltage at one-half the supply. Amplifier A1 then buffers this voltage creating a low impedance output drive. The S/H circuit is configured in an inverting topology centered around this false ground level.

## AD824

A design consideration in sample-and-hold circuits is voltage droop at the output caused by op amp bias and switch leakage currents. By choosing a JFET op amp and a low leakage CMOS switch, this design minimizes droop rate error to better than  $0.1 \mu\text{V}/\mu\text{s}$  in this circuit. Higher values of  $C_H$  will yield a lower droop rate. For best performance,  $C_H$  and  $C_2$  should be polystyrene, polypropylene or Teflon capacitors. These types of capacitors exhibit low leakage and low dielectric absorption. Additionally, 1% metal film resistors were used throughout the design.

In the sample mode, SW1 and SW4 are closed, and the output is  $V_{\text{OUT}} = -V_{\text{IN}}$ . The purpose of SW4, which operates in parallel with SW1, is to reduce the pedestal, or hold step, error by injecting the same amount of charge into the noninverting input of A3 that SW1 injects into the inverting input of A3. This creates a common-mode voltage across the inputs of A3 and is then rejected by the CMR of A3; otherwise, the charge injection from SW1 would create a differential voltage step error that would appear at  $V_{\text{OUT}}$ . The pedestal error for this circuit is

less than 2 mV over the entire 0 V to 3.3 V/5 V signal range. Another method of reducing pedestal error is to reduce the pulse amplitude applied to the control pins. In order to control the ADG513, only 2.4 V are required for the “ON” state and 0.8 V for the “OFF” state. If possible, use an input control signal whose amplitude ranges from 0.8 V to 2.4 V instead of a full range 0 V to 3.3 V/5 V for minimum pedestal error.

Other circuit features include an acquisition time of less than  $3 \mu\text{s}$  to 1%; reducing  $C_H$  and  $C_2$  will speed up the acquisition time further, but an increased pedestal error will result. Settling time is less than 300 ns to 1%, and the sample-mode signal BW is 80 kHz.

The ADG513 was chosen for its ability to work with 3 V/5 V supplies and for having normally open and normally closed precision CMOS switches on a dielectrically isolated process. SW2 is not required in this circuit; however, it was used in parallel with SW3 to provide a lower  $R_{\text{ON}}$  analog switch.

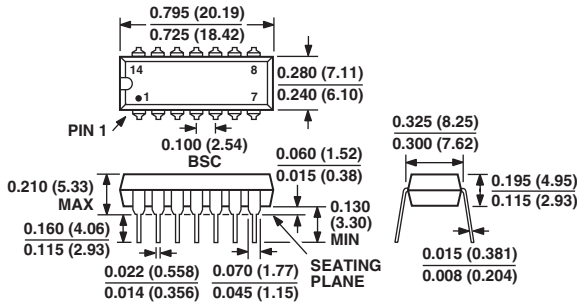
* AD824 SPICE Macro-model	9/94, Rev. A *	G15 98	18
ARG/ADI		(9,98) 1E-6	
*		*	
* Copyright 1994 by Analog Devices, Inc.		* OUTPUT STAGE	
*		*	
* Refer to "README.DOC" file for License Statement.		ES 26	98
Use of this model indicates your acceptance with		(18,98) 1	
the terms and provisions in the License Statement. *		RS 26	22
* Node assignments		500	
*	noninverting input	IB1 98	21
*	inverting input	2.404E-3	
*	positive supply	IB2 23	98
*	negative supply	2.404E-3	
*	output	D10 21	98
*		DY	
.SUBCKT AD824		D11 98	23
1 2 99 50 25		DY	
*		C16 20	25
* INPUT STAGE & POLE AT 3.1 MHz		2E-12	
*		C17 24	25
R3 5	99	2E-12	
1.193E3		DQ197	20
R4 6	99	DQ	
1.193E3		Q2 20	21
CIN 1	2	22 NPN	
4E-12		Q3 24	23
C2 5	6	22 PNP	
19.229E-12		DQ224	51
I1 4 50	108E-6	DQ	
IOS 1	2	Q5 25	20
1E-12		97 PNP 20	
EOS 7	1	Q6 25	24
POLY(1) (12,98) 100E-6 1		51 NPN 20	
J1 4 2	5	VP 96	97
JX		0	
J2 4 7	6	VN 51	52
JX		0	
*		EP 96	0
* GAIN STAGE & DOMINANT POLE		(99,0) 1	
*		EN 52	0
EREF	98	(50,0) 1	
0 (30,0) 1		R25 30	99
R5 9	98	5E6	
2.205E6		R26 30	50
C3 9	25	5E6	
54E-12		FSY1	99
G1 98	9	0 VP 1	
(6,5) 0.838E-3		FSY2	0
V1 8	98	50VN 1	
-1		DC1 25	99
V2 98	10	DX	
-1		DC2 50	25
D1 9	10	DX	
DX		*	
D2 8	9	* MODELS USED	
DX		*	
* COMMON-MODE GAIN NETWORK WITH ZERO AT 1 kHz *		.MODEL JX NJF(BETA=3.2526E-3 VTO=-2.000 IS=2E-12) .MODEL	
R21 11	12	NPN NPN(BF=120 VAF=150 VAR=15 RB=2E3	
1E6		+ RE=4 RC=550 IS=1E-16)	
R22 12	98	.MODEL PNP PNP(BF=120 VAF=150 VAR=15 RB=2E3 + RE=4	
100		RC=750 IS=1E-16)	
C14 11	12	.MODEL DX D(IS=1E-15)	
159E-12		.MODEL DY D()	
E13 11	98	.MODEL DQ D(IS=1E-16)	
POLY(2) (2,98) (1,98) 0 0.5 0.5		.ENDS AD824	
*			
* POLE AT 10 MHz			
*			
R23 18	98		
1E6			
C15 18	98		
15.9E-15			

# AD824

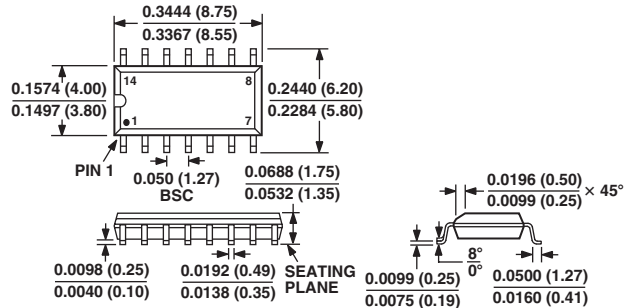
## OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

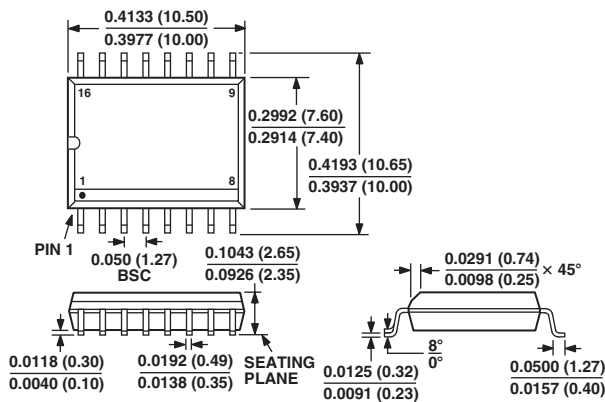
### 14-Pin Plastic (N) Package (N-14)



### 14-Pin SOIC (R) Package (R-14)



### 16-Pin SOIC Package (R-16)



## Revision History

Location	Page
<b>Data Sheet changed from REV. A to REV. B.</b>	
Edits to ELECTRICAL SPECIFICATIONS . . . . .	2, 3
Edits to ABSOLUTE MAXIMUM RATINGS . . . . .	5
Edits to ORDERING GUIDE . . . . .	5
Deleted DICE CHARACTERISTICS . . . . .	5