MOTOROLA
MPX2050

SEMICONDUCTOR TECHNICAL DATA

PCB   24

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by MPX2050/D

50 kPa On-Chip Temperature Compensated & Calibrated Silicon Pressure Sensors

The MPX2050 series device is a silicon piezoresistive pressure sensors providing a highly accurate and linear voltage output — directly proportional to the applied pressure. The sensor is a single, monolithic silicon diaphragm with the strain gauge and a thin–film resistor network integrated on–chip. The chip is laser trimmed for precise span and offset calibration and temperature compensation.

Features

- Temperature Compensated Over 0°C to +85°C
- Unique Silicon Shear Stress Strain Gauge
- Easy to Use Chip Carrier Package Options
- Ratiometric to Supply Voltage
- Differential and Gauge Options
- ±0.25% Linearity (MPX2050)

Application Examples

- Pump/Motor Controllers
- Robotics
- Level Indicators
- Medical Diagnostics
- Pressure Switching
- Non–Invasive Blood Pressure Measurement

Figure 1 shows a block diagram of the internal circuitry on the stand–alone pressure sensor chip.
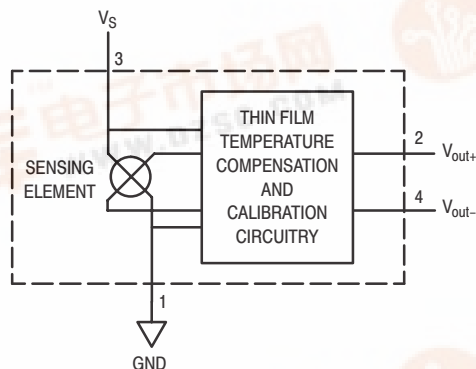
MPX2050 SERIES

0 to 50 kPa (0 to 7.25 psi) 40 mV FULL SCALE SPAN (TYPICAL)

MPX2050D
CASE 344

MPX2050GP
CASE 344B

MPX2050DP
CASE 344C

MPX2050GSX
CASE 344F

Figure 1. Temperature Compensated Pressure Sensor Schematic
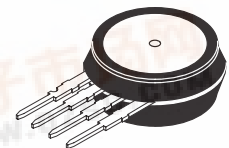
VOLTAGE OUTPUT versus APPLIED DIFFERENTIAL PRESSURE

The differential voltage output of the sensor is directly proportional to the differential pressure applied.
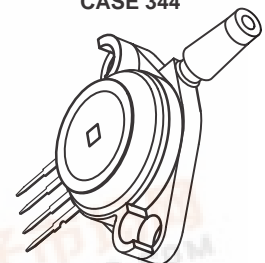
The output voltage of the differential or gauge sensor increases with increasing pressure applied to the pressure side (P1) relative to the vacuum side (P2). Similarly, output voltage increases as increasing vacuum is applied to the vacuum side (P2) relative to the pressure side (P1).
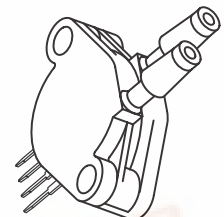
PIN NUMBER

1	Gnd	3	V_S
2	$+V_{out}$	4	$-V_{out}$

NOTE: Pin 1 is noted by the notch in the lead.

REV 8

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MPX2050 SERIES

MAXIMUM RATINGS[NOTE]

Rating	Symbol	Value	Unit
Maximum Pressure (P1 > P2)	P_{max}	200	kPa
Storage Temperature	T_{stg}	−40 to +125	°C
Operating Temperature	T_A	−40 to +125	°C

NOTE: Exposure beyond the specified limits may cause permanent damage or degradation to the device.

OPERATING CHARACTERISTICS (V_S = 10 Vdc, T_A = 25°C unless otherwise noted, P1 > P2)

Characteristic		Symbol	Min	Typ	Max	Unit
Pressure Range[1]		P_{OP}	0	—	50	kPa
Supply Voltage[2]		V_S	—	10	16	Vdc
Supply Current		I_o	—	6.0	—	mAdc
Full Scale Span[3]	MPX2050	V_{FSS}	38.5	40	41.5	mV
Offset[4]	MPX2050	V_{off}	−1.0	—	1.0	mV
Sensitivity		$\Delta V/\Delta P$	—	0.8	—	mV/kPa
Linearity[5]	MPX2050		—	−0.25	—	0.25	%V_{FSS}
Pressure Hysteresis[5] (0 to 50 kPa)		—	—	±0.1	—	%V_{FSS}
Temperature Hysteresis[5] (−40°C to +125°C)		—	—	±0.5	—	%V_{FSS}
Temperature Effect on Full Scale Span[5]		TCV_{FSS}	−1.0	—	1.0	%V_{FSS}
Temperature Effect on Offset[5]		TCV_{off}	−1.0	—	1.0	mV
Input Impedance		Z_{in}	1000	—	2500	Ω
Output Impedance		Z_{out}	1400	—	3000	Ω
Response Time[6] (10% to 90%)		t_R	—	1.0	—	ms
Warm–Up		—	—	20	—	ms
Offset Stability[7]		—	—	±0.5	—	%V_{FSS}

NOTES:
1. 1.0 kPa (kiloPascal) equals 0.145 psi.
2. Device is ratiometric within this specified excitation range. Operating the device above the specified excitation range may induce additional error due to device self–heating.
3. Full Scale Span (V_{FSS}) is defined as the algebraic difference between the output voltage at full rated pressure and the output voltage at the minimum rated pressure.
4. Offset (V_{off}) is defined as the output voltage at the minimum rated pressure.
5. Accuracy (error budget) consists of the following:
    - Linearity: Output deviation from a straight line relationship with pressure, using end point method, over the specified pressure range.
    - Temperature Hysteresis: Output deviation at any temperature within the operating temperature range, after the temperature is cycled to and from the minimum or maximum operating temperature points, with zero differential pressure applied.
    - Pressure Hysteresis: Output deviation at any pressure within the specified range, when this pressure is cycled to and from the minimum or maximum rated pressure, at 25°C.
    - TcSpan: Output deviation at full rated pressure over the temperature range of 0 to 85°C, relative to 25°C.
    - TcOffset: Output deviation with minimum rated pressure applied, over the temperature range of 0 to 85°C, relative to 25°C.
6. Response Time is defined as the time for the incremental change in the output to go from 10% to 90% of its final value when subjected to a specified step change in pressure.
7. Offset stability is the product's output deviation when subjected to 1000 hours of Pulsed Pressure, Temperature Cycling with Bias Test.

LINEARITY

Linearity refers to how well a transducer's output follows the equation: $V_{out} = V_{off}$ + sensitivity x P over the operating pressure range. There are two basic methods for calculating nonlinearity: (1) end point straight line fit (see Figure 2) or (2) a least squares best line fit. While a least squares fit gives the "best case" linearity error (lower numerical value), the calculations required are burdensome.

Conversely, an end point fit will give the "worst case" error (often more desirable in error budget calculations) and the calculations are more straightforward for the user. Motorola's specified pressure sensor linearities are based on the end point straight line method measured at the midrange pressure.
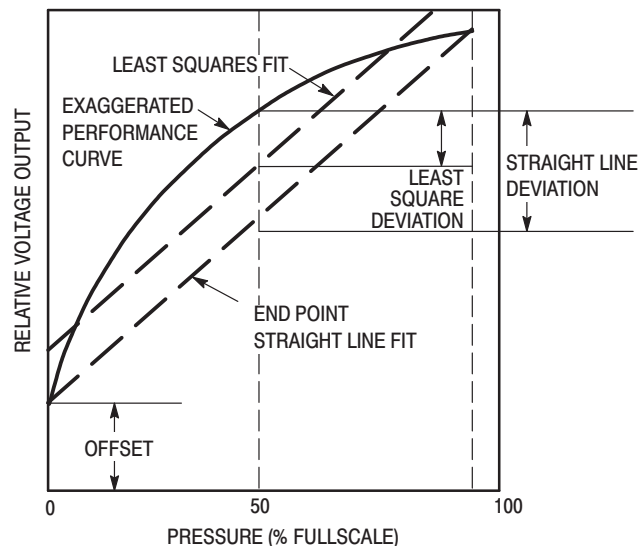

Figure 2. Linearity Specification Comparison

ON–CHIP TEMPERATURE COMPENSATION and CALIBRATION

Figure 3 shows the minimum, maximum and typical output characteristics of the MPX2050 series at 25°C. The output is directly proportional to the differential pressure and is essentially a straight line.
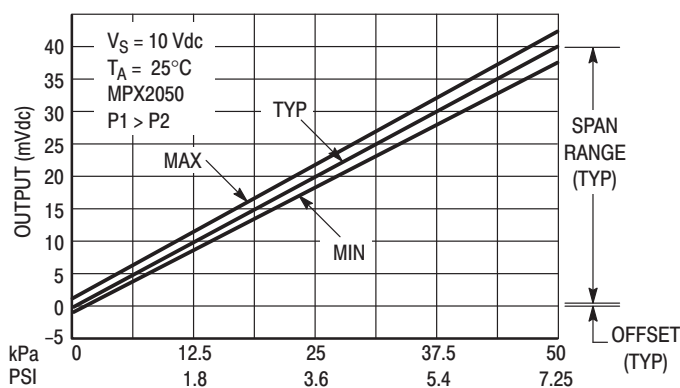
The effects of temperature on Full–Scale Span and Offset are very small and are shown under Operating Characteristics.

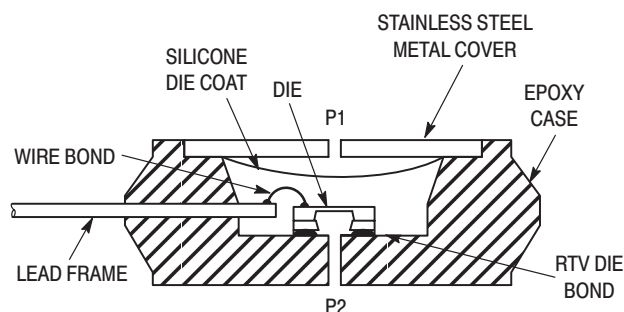**Figure 3. Output versus Pressure Differential**

Figure 4. Cross–Sectional Diagram (not to scale)

Figure 4 illustrates the differential or gauge configuration in the basic chip carrier (Case 344). A silicone gel isolates the die surface and wire bonds from the environment, while allowing the pressure signal to be transmitted to the silicon diaphragm.

The MPX2050 series pressure sensor operating charac-teristics and internal reliability and qualification tests are based on use of dry air as the pressure media. Media other than dry air may have adverse effects on sensor perfor-mance and long term reliability. Contact the factory for in-formation regarding media compatibility in your application.

PRESSURE (P1)/VACUUM (P2) SIDE IDENTIFICATION TABLE

Motorola designates the two sides of the pressure sensor as the Pressure (P1) side and the Vacuum (P2) side. The Pressure (P1) side is the side containing the silicone gel which isolates the die. The Motorola MPX pressure sensor is designed to operate with positive differential pressure applied, P1 > P2.

The Pressure (P1) side may be identified by using the table below:

| Part Number	Case Type	Pressure (P1) Side Identifier
MPX2050D	344	Stainless Steel Cap
MPX2050DP	344C	Side with Part Marking
MPX2050GP	344B	Side with Port Attached
MPX2050GSX	344F	Side with Port Attached

ORDERING INFORMATION

MPX2050 series pressure sensors are available in differential and gauge configurations. Devices are available in the basic element package or with pressure port fittings which provide printed circuit board mounting ease and barbed hose pressure connections.

Device Type	Options	Case Type	MPX Series	
			Order Number	Device Marking
Basic Element	Differential	344	MPX2050D	MPX2050D
Ported Elements	Differential, Dual Port	344C	MPX2050DP	MPX2050DP
	Gauge	344B	MPX2050GP	MPX2050GP
	Gauge Axial PC Mount	344F	MPX2050GSX	MPX2050D

PACKAGE DIMENSIONS
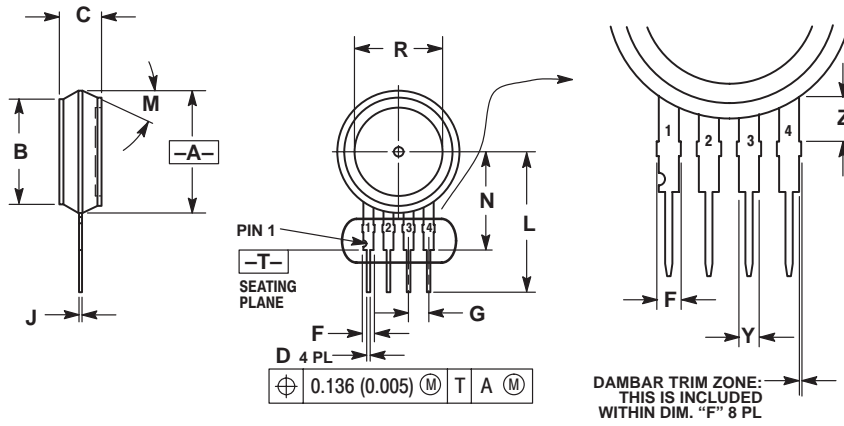
NOTES:
1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION –A– IS INCLUSIVE OF THE MOLD STOP RING. MOLD STOP RING NOT TO EXCEED 16.00 (0.630).

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.595	0.630	15.11	16.00
B	0.514	0.534	13.06	13.56
C	0.200	0.220	5.08	5.59
D	0.016	0.020	0.41	0.51
F	0.048	0.064	1.22	1.63
G	0.100 BSC		2.54 BSC	
J	0.014	0.016	0.36	0.40
L	0.695	0.725	17.65	18.42
M	30° NOM		30° NOM	
N	0.475	0.495	12.07	12.57
R	0.430	0.450	10.92	11.43
Y	0.048	0.052	1.22	1.32
Z	0.106	0.118	2.68	3.00

DAMBAR TRIM ZONE:
THIS IS INCLUDED
WITHIN DIM. "F" 8 PL

STYLE 1:
PIN 1. GROUND
2. + OUTPUT
3. + SUPPLY
4. – OUTPUT

STYLE 2:
PIN 1. V_{CC}
2. – SUPPLY
3. + SUPPLY
4. GROUND

STYLE 3:
PIN 1. GND
2. –VOUT
3. VS
4. +VOUT

CASE 344–15
ISSUE Z
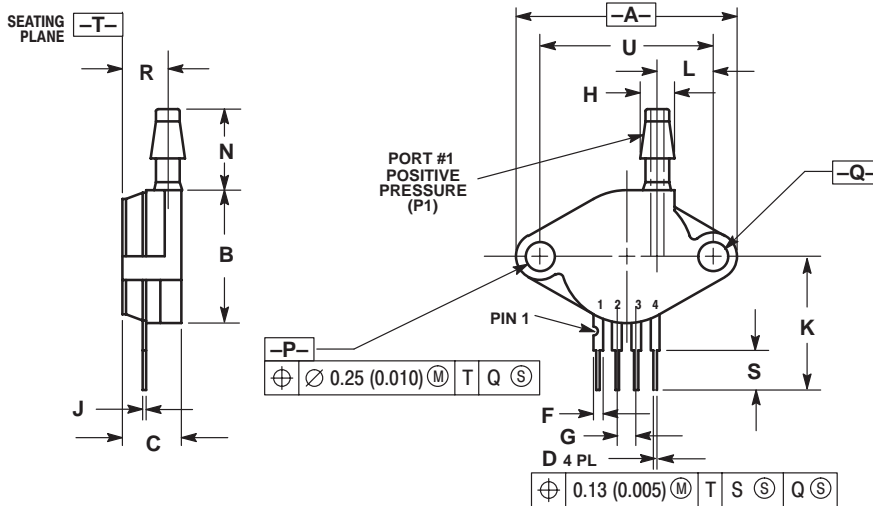
NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5, 1982.
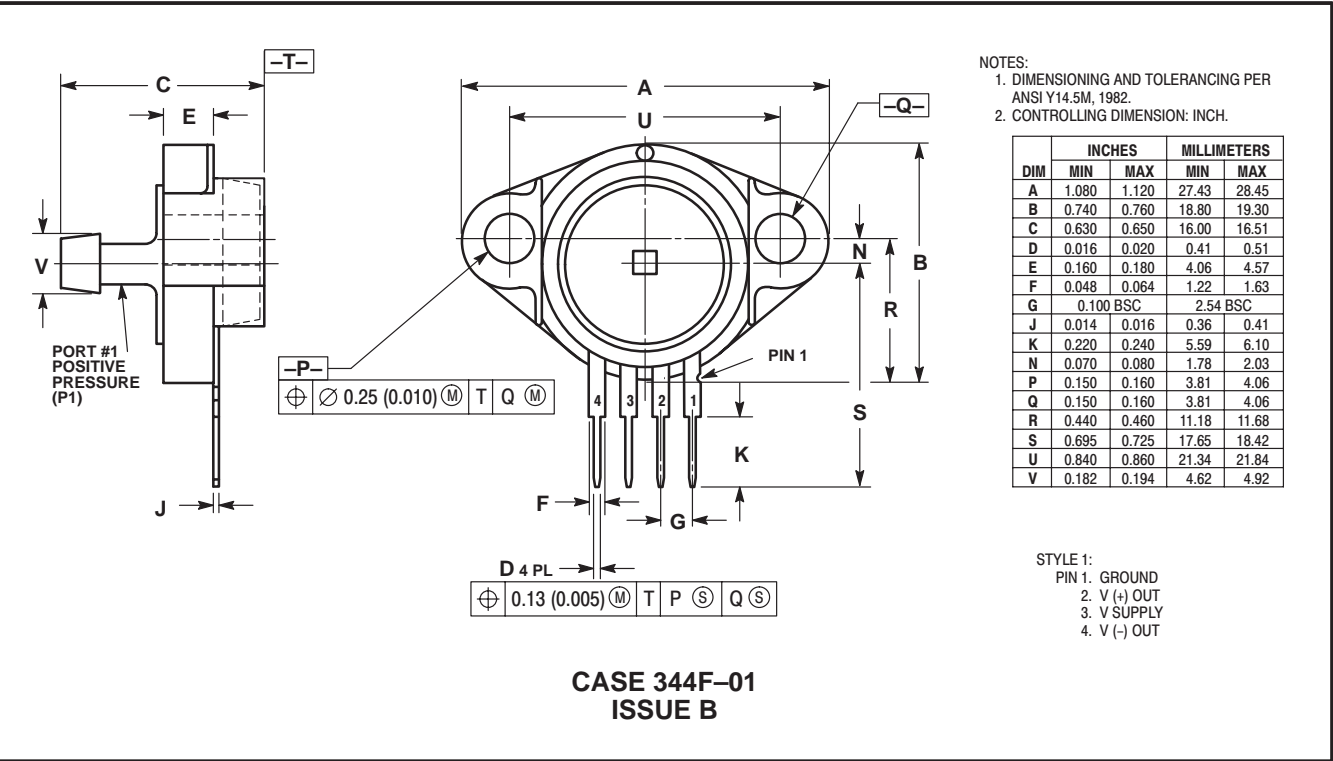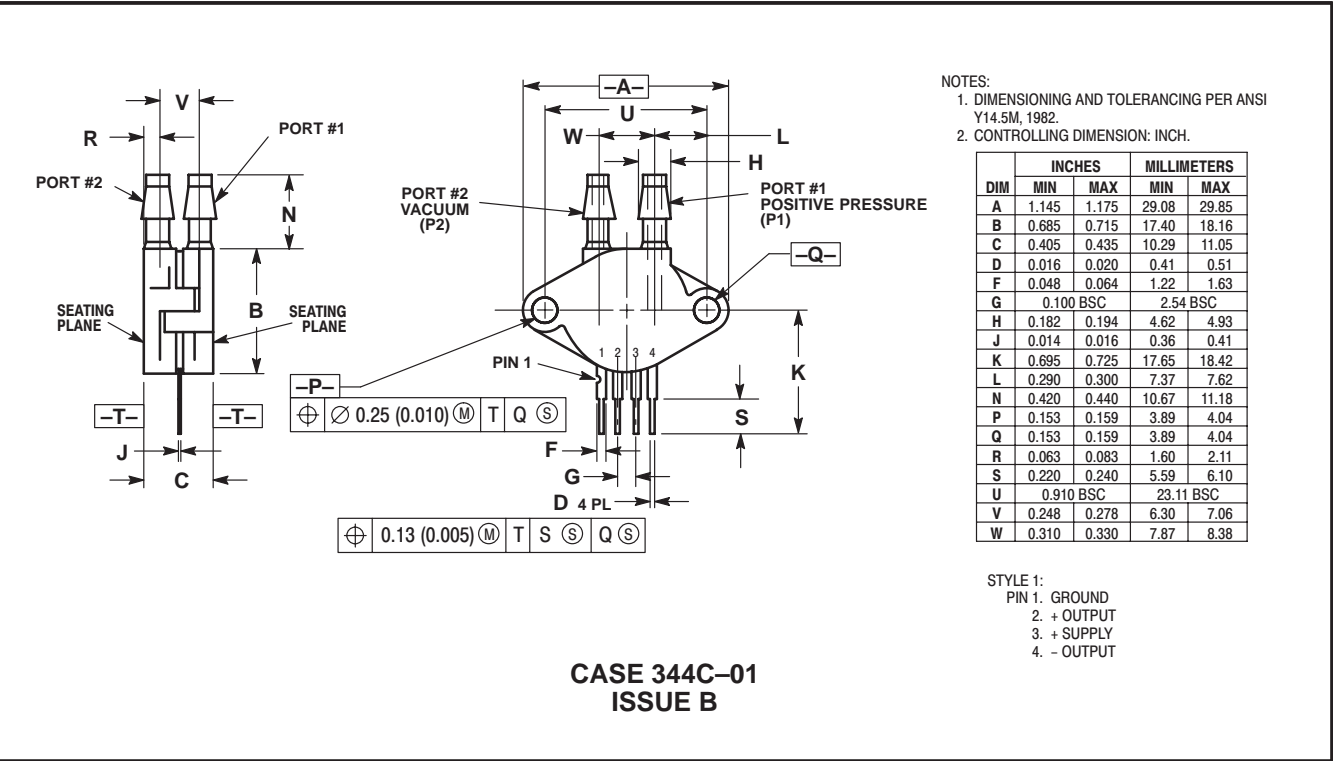2. CONTROLLING DIMENSION: INCH.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	1.145	1.175	29.08	29.85
B	0.685	0.715	17.40	18.16
C	0.305	0.325	7.75	8.26
D	0.016	0.020	0.41	0.51
F	0.048	0.064	1.22	1.63
G	0.100 BSC		2.54 BSC	
H	0.182	0.194	4.62	4.93
J	0.014	0.016	0.36	0.41
K	0.695	0.725	17.65	18.42
L	0.290	0.300	7.37	7.62
N	0.420	0.440	10.67	11.18
P	0.153	0.159	3.89	4.04
Q	0.153	0.159	3.89	4.04
R	0.230	0.250	5.84	6.35
S	0.220	0.240	5.59	6.10
U	0.910 BSC		23.11 BSC	

PORT #1
POSITIVE
PRESSURE
(P1)

STYLE 1:
PIN 1. GROUND
2. + OUTPUT
3. + SUPPLY
4. – OUTPUT

CASE 344B–01
ISSUE B

PACKAGE DIMENSIONS — CONTINUED

NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	1.145	1.175	29.08	29.85
B	0.685	0.715	17.40	18.16
C	0.405	0.435	10.29	11.05
D	0.016	0.020	0.41	0.51
F	0.048	0.064	1.22	1.63
G	0.100 BSC		2.54 BSC	
H	0.182	0.194	4.62	4.93
J	0.014	0.016	0.36	0.41
K	0.695	0.725	17.65	18.42
L	0.290	0.300	7.37	7.62
N	0.420	0.440	10.67	11.18
P	0.153	0.159	3.89	4.04
Q	0.153	0.159	3.89	4.04
R	0.063	0.083	1.60	2.11
S	0.220	0.240	5.59	6.10
U	0.910 BSC		23.11 BSC	
V	0.248	0.278	6.30	7.06
W	0.310	0.330	7.87	8.38

STYLE 1:
PIN 1. GROUND
2. + OUTPUT
3. + SUPPLY
4. – OUTPUT

CASE 344C–01
ISSUE B

NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	1.080	1.120	27.43	28.45
B	0.740	0.760	18.80	19.30
C	0.630	0.650	16.00	16.51
D	0.016	0.020	0.41	0.51
E	0.160	0.180	4.06	4.57
F	0.048	0.064	1.22	1.63
G	0.100 BSC		2.54 BSC	
J	0.014	0.016	0.36	0.41
K	0.220	0.240	5.59	6.10
N	0.070	0.080	1.78	2.03
P	0.150	0.160	3.81	4.06
Q	0.150	0.160	3.81	4.06
R	0.440	0.460	11.18	11.68
S	0.695	0.725	17.65	18.42
U	0.840	0.860	21.34	21.84
V	0.182	0.194	4.62	4.92

STYLE 1:
PIN 1. GROUND
2. V (+) OUT
3. V SUPPLY
4. V (–) OUT

CASE 344F–01
ISSUE B

NOTES