

## 1.2 A/1.25 MHz, HIGH-EFFICIENCY STEP-DOWN CONVERTER

### FEATURES

- Up to 95% Conversion Efficiency
- Typical Quiescent Current: 18  $\mu$ A
- Load Current: 1.2 A
- Operating Input Voltage Range: 2.5 V to 6.0 V
- Switching Frequency: 1.25 MHz
- Adjustable and Fixed Output Voltage
- Power Save Mode Operation at Light load Currents
- 100% Duty Cycle for Lowest Dropout
- Internal Softstart
- Dynamic Output Voltage Positioning
- Thermal Shutdown
- Short-Circuit Protection
- 10 Pin MSOP PowerPad™ Package
- 10 Pin QFN 3 X 3 mm Package

### APPLICATIONS

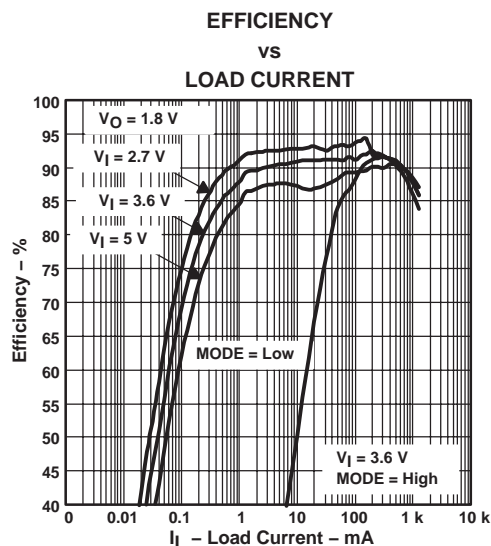
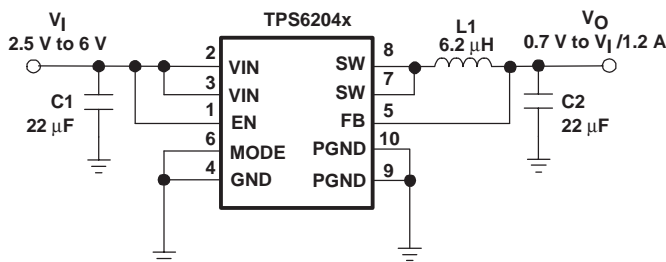
- PDA, Pocket PC and Smart Phones

- USB Powered Modems
- CPUs and DSPs
- PC Cards and Notebooks
- xDSL Applications
- Standard 5-V to 3.3-V Conversion

### DESCRIPTION

The TPS6204x family of devices are high efficiency synchronous step-down dc-dc converters optimized for battery powered portable applications. The devices are ideal for portable applications powered by a single Li-Ion battery cell or by 3-cell NiMH/NiCd batteries. With an output voltage range from 6.0 V down to 0.7 V, the devices support low voltage DSPs and processors in PDAs, pocket PCs, as well as notebooks and subnotebook computers. The TPS6204x operates at a fixed switching frequency of 1.25 MHz and enters the power save mode operation at light load currents to maintain high efficiency over the entire load current range. For low noise applications, the devices can be forced into fixed frequency PWM mode by pulling the MODE pin high. The TPS6204x supports up to 1.2-A load current.

Typical Application Circuit 1.2-A Output Current



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PowerPAD is a trademark of Texas Instruments.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## ORDERING INFORMATION

| T <sub>A</sub> | VOLTAGE OPTIONS | PACKAGE             |                    | PACKAGE MARKING |     |
|----------------|-----------------|---------------------|--------------------|-----------------|-----|
|                |                 | MSOP <sup>(1)</sup> | QFN <sup>(2)</sup> | MSOP            | QFN |
| –40°C to 85°C  | Adjustable      | TPS62040DGQ         | TPS62040DRC        | BBI             | BBO |
|                | 1.5 V           | TPS62042DGQ         | TPS62042DRC        | BBL             | BBS |
|                | 1.6 V           | TPS62043DGQ         | TPS62043DRC        | BBM             | BBT |
|                | 1.8 V           | TPS62044DGQ         | TPS62044DRC        | BBN             | BBU |
|                | 3.3 V           | TPS62046DGQ         | TPS62046DRC        | BBQ             | BBW |

(1) The DGQ package is available in tape and reel. Add R suffix (DGQR) to order quantities of 2500 parts per reel.

(2) The DRC package is available in tape and reel. Add R suffix (DRCR) to order quantities of 3000 parts per reel.

## ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted<sup>(1)</sup>

|   | UNITS                            |
|---|----------------------------------|
| Supply voltage V <sub>IN</sub> (2)          | –0.3 V to 7 V                    |
| Voltages on EN, MODE, FB, SW <sup>(2)</sup> | –0.3 V to V <sub>CC</sub> +0.3 V |
| Continuous power dissipation                | See Dissipation Rating Table     |
| Operating junction temperature range        | –40°C to 150°C                   |
| Storage temperature range                   | –65°C to 150°C                   |
| Lead temperature (soldering, 10 sec)        | 260°C                            |

(1) Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

## PACKAGE DISSIPATION RATINGS

| PACKAGE | R <sub>ΘJA</sub> <sup>(1)</sup> | T <sub>A</sub> ≤ 25°C<br>POWER RATING | T <sub>A</sub> = 70°C<br>POWER RATING | T <sub>A</sub> = 85°C<br>POWER RATING |
|---------|---------------------------------|---------------------------------------|---------------------------------------|---------------------------------------|
| MSOP    | 60°C/W                          | 1.67 W                                | 917 mW                                | 667 mW                                |
| QFN     | 48.7°C/W                        | 2.05 W                                | 1.13 W                                | 821 mW                                |

(1) The thermal resistance, R<sub>ΘJA</sub> is based on a soldered PowerPAD using thermal vias.

## RECOMMENDED OPERATING CONDITIONS

|   | MIN | TYP | MAX            | UNIT |
|---|-----|-----|----------------|------|
| V <sub>I</sub> Supply voltage   | 2.5 |     | 6.0            | V    |
| V <sub>O</sub> Output voltage range for adjustable output voltage version | 0.7 |     | V <sub>I</sub> | V    |
| I <sub>O</sub> Output current   |     |     | 1.2            | A    |
| L Inductor <sup>(1)</sup>   |     | 6.2 |                | μH   |
| C <sub>I</sub> Input capacitor <sup>(1)</sup>                             |     | 22  |                | μF   |
| C <sub>O</sub> Output capacitor <sup>(1)</sup>                            |     | 22  |                | μF   |
| T <sub>A</sub> Operating ambient temperature                              | –40 |     | 85             | °C   |
| T <sub>J</sub> Operating junction temperature                             | –40 |     | 125            | °C   |

(1) Refer to application section for further information

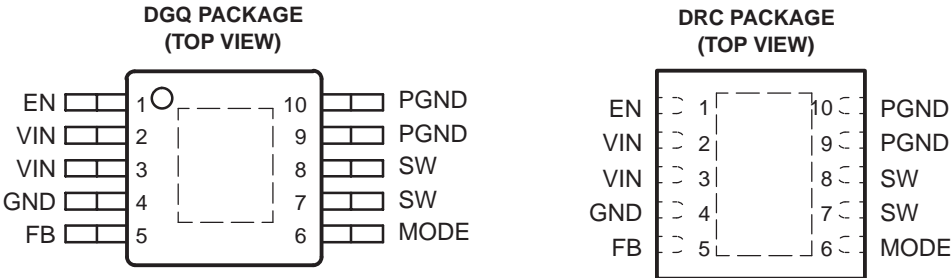
## ELECTRICAL CHARACTERISTICS

 $V_I = 3.6\text{ V}$ ,  $V_O = 1.8\text{ V}$ ,  $I_O = 600\text{ mA}$ ,  $EN = VIN$ ,  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$ , typical values are at  $T_A = 25^\circ\text{C}$  (unless otherwise noted)<sup>(1)</sup>

| SUPPLY CURRENT                 |                                     |                     |  |  |           |      |                 |      |
|--------------------------------|-------------------------------------|---------------------|--|--|-----------|------|-----------------|------|
| PARAMETER                      |                                     |                     | TEST CONDITIONS  |  | MIN       | TYP  | MAX             | UNIT |
| V <sub>I</sub>                 | Input voltage range                 |                     |  |  | 2.5       |      | 6.0             | V    |
| I <sub>(Q)</sub>               | Operating quiescent current         |                     | I <sub>O</sub> = 0 mA, device is not switching   |  |           | 18   | 35              | μA   |
| I <sub>SD</sub>                | Shutdown supply current             |                     | EN = GND   |  |           | 0.1  | 1               | μA   |
| V <sub>UVLO</sub>              | Under-voltage lockout threshold     |                     |  |  | 1.5       |      | 2.3             | V    |
| ENABLE AND MODE                |                                     |                     |  |  |           |      |                 |      |
| V <sub>EN</sub>                | EN high level input voltage         |                     |  |  | 1.4       |      |                 | V    |
| V <sub>EN</sub>                | EN low level input voltage          |                     |  |  |           |      | 0.4             | V    |
| I <sub>EN</sub>                | EN input bias current               |                     | EN = GND or V <sub>IN</sub>  |  |           | 0.01 | 1.0             | μA   |
| V <sub>(MODE)</sub>            | MODE high level input voltage       |                     |  |  | 1.4       |      |                 | V    |
| V <sub>(MODE)</sub>            | MODE low level input voltage        |                     |  |  |           |      | 0.4             | V    |
| I <sub>(MODE)</sub>            | MODE input bias current             |                     | MODE = GND or V <sub>IN</sub>  |  |           | 0.01 | 1.0             | μA   |
| POWER SWITCH                   |                                     |                     |  |  |           |      |                 |      |
| r <sub>DS(ON)</sub>            | P-channel MOSFET on-resistance      |                     | V <sub>I</sub> = V <sub>GS</sub> = 3.6 V   |  |           | 115  | 210             | mΩ   |
|                                | P-channel MOSFET on-resistance      |                     | V <sub>I</sub> = V <sub>GS</sub> = 2.5 V   |  |           | 145  | 270             | mΩ   |
| I <sub>lkg(P)</sub>            | P-channel leakage current           |                     | V <sub>DS</sub> = 6.0 V  |  |           |      | 1               | μA   |
| r <sub>DS(ON)</sub>            | N-channel MOSFET on-resistance      |                     | V <sub>I</sub> = V <sub>GS</sub> = 3.6 V   |  |           | 85   | 200             | mΩ   |
|                                | N-channel MOSFET on-resistance      |                     | V <sub>I</sub> = V <sub>GS</sub> = 2.5 V   |  |           | 115  | 280             | mΩ   |
| I <sub>lkg(N)</sub>            | N-channel leakage current           |                     | V <sub>DS</sub> = 6.0 V  |  |           |      | 1               | μA   |
| I <sub>L</sub>                 | P-channel current limit             |                     | 2.5 V < V <sub>I</sub> < 6.0 V   |  | 1.5       | 1.85 | 2.2             | A    |
| Thermal shutdown               |                                     |                     |  |  |           | 150  |                 | °C   |
| OSCILLATOR                     |                                     |                     |  |  |           |      |                 |      |
| f <sub>S</sub>                 | Oscillator frequency                |                     | V <sub>FB</sub> = 0.5 V  |  | 1         | 1.25 | 1.5             | MHz  |
|                                |                                     |                     | V <sub>FB</sub> = 0 V  |  |           | 625  |                 | kHz  |
| OUTPUT                         |                                     |                     |  |  |           |      |                 |      |
| V <sub>O</sub>                 | Adjustable output voltage range     | TPS62040            |  |  | 0.7       |      | V <sub>IN</sub> | V    |
| V <sub>ref</sub>               | Reference voltage                   |                     |  |  |           | 0.5  |                 | V    |
| V <sub>FB</sub>                | Feedback voltage                    | TPS62040 Adjustable | V <sub>I</sub> = 2.5 V to 6.0 V; I <sub>O</sub> = 0 mA<br>V <sub>I</sub> = 2.5 V to 6.0 V; 0 mA ≤ I <sub>O</sub> ≤ 1.2 A |  | 0%<br>–3% |      | 3%<br>3%        |      |
| V <sub>O</sub>                 | Fixed output voltage                | TPS62042 1.5V       | V <sub>I</sub> = 2.5 V to 6.0 V; I <sub>O</sub> = 0 mA<br>V <sub>I</sub> = 2.5 V to 6.0 V; 0 mA ≤ I <sub>O</sub> ≤ 1.2 A |  | 0%<br>–3% |      | 3%<br>3%        |      |
|                                |                                     | TPS62043 1.6V       | V <sub>I</sub> = 2.5 V to 6.0 V; I <sub>O</sub> = 0 mA<br>V <sub>I</sub> = 2.5 V to 6.0 V; 0 mA ≤ I <sub>O</sub> ≤ 1.2 A |  | 0%<br>–3% |      | 3%<br>3%        |      |
|                                |                                     | TPS62044 1.8V       | V <sub>I</sub> = 2.5 V to 6.0 V; I <sub>O</sub> = 0 mA<br>V <sub>I</sub> = 2.5 V to 6.0 V; 0 mA ≤ I <sub>O</sub> ≤ 1.2 A |  | 0%<br>–3% |      | 3%<br>3%        |      |
|                                |                                     | TPS62046 3.3V       | V <sub>I</sub> = 3.6 V to 6.0 V; I <sub>O</sub> = 0 mA<br>V <sub>I</sub> = 3.6 V to 6.0 V; 0 mA ≤ I <sub>O</sub> ≤ 1.2 A |  | 0%<br>–3% |      | 3%<br>3%        |      |
| Line regulation <sup>(1)</sup> |                                     |                     | V <sub>I</sub> = V <sub>O</sub> + 0.5 V (min. 2.5 V) to 6.0 V, I <sub>O</sub> = 10 mA                                    |  |           | 0    |                 | %/V  |
| Load regulation <sup>(1)</sup> |                                     |                     | I <sub>O</sub> = 10 mA to 1200 mA  |  |           | 0    |                 | %/mA |
| I <sub>lkg(SW)</sub>           | Leakage current into SW pin         |                     | V <sub>I</sub> > V <sub>O</sub> , 0 V ≤ V <sub>SW</sub> ≤ V <sub>I</sub>   |  |           | 0.1  | 1               | μA   |
|                                | Reverse leakage current into pin SW |                     | V <sub>I</sub> = open; EN = GND; V <sub>SW</sub> = 6.0 V   |  |           | 0.1  | 1               | μA   |
| f                              | Short circuit switching frequency   |                     | V <sub>FB</sub> = 0 V  |  |           | 625  |                 | kHz  |

<sup>(1)</sup> The line and load regulations are digitally controlled to assure an output voltage accuracy of  $\pm 3\%$ .

## PIN ASSIGNMENTS

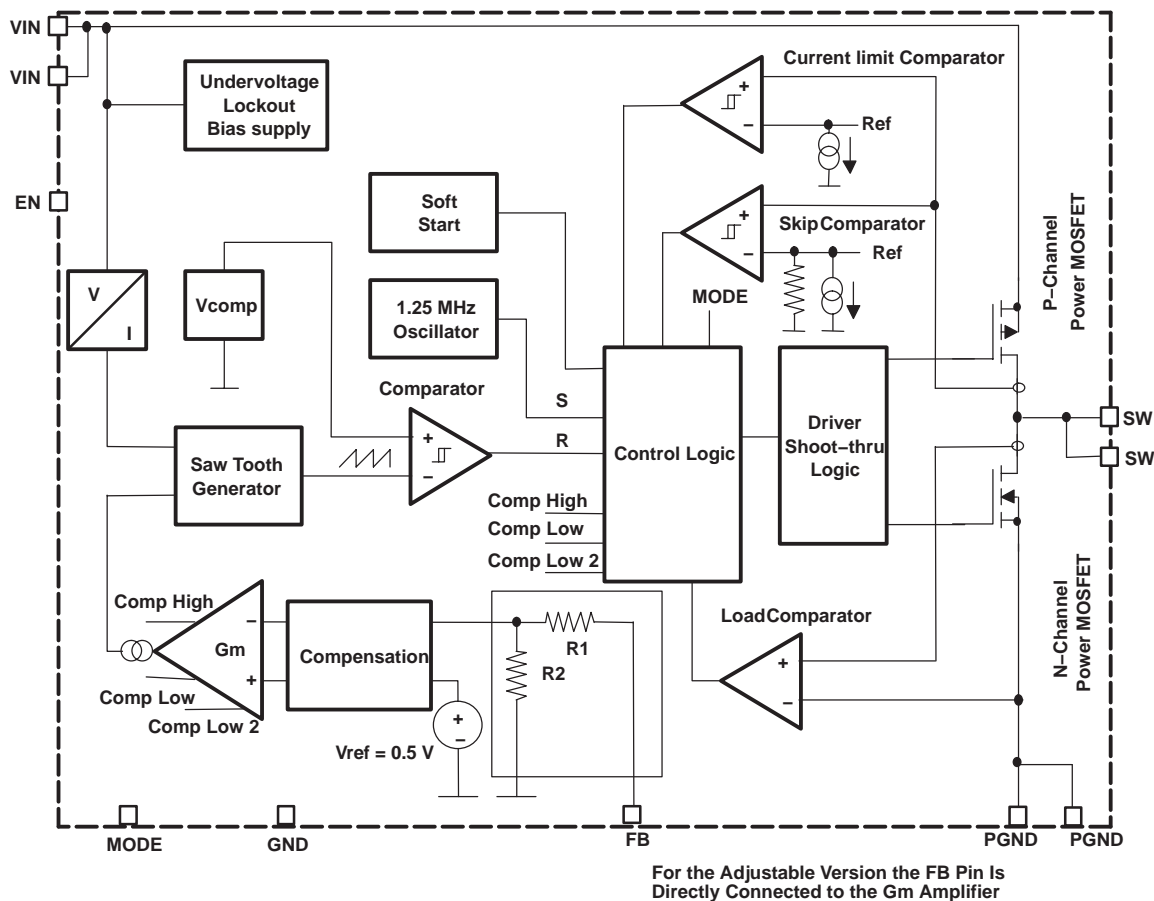


NOTE: The PowerPAD must be connected to GND.

## Terminal Functions

| TERMINAL<br>NAME | NO.  | I/O | DESCRIPTION   |
|------------------|------|-----|---|
| EN               | 1    | I   | Enable. Pulling EN to ground forces the device into shutdown mode. Pulling EN to $V_I$ enables the device. EN should not be left floating and must be terminated.   |
| VIN              | 2,3  | I   | Supply voltage input  |
| GND              | 4    |     | Analog ground   |
| FB               | 5    | I   | Feedback pin. Connect FB directly to the output if the fixed output voltage version is used. For the adjustable version an external resistor divider is connected to this pin. The internal voltage divider is disabled for the adjustable version.   |
| MODE             | 6    | I   | Pulling the MODE pin high allows the device to be forced into fixed frequency operation. Pulling the MODE pin to low enables the power save mode where the device operates in fixed frequency PWM mode at high load currents and in PFM mode (pulse frequency modulation) at light load currents. |
| SW               | 7,8  | I/O | This is the switch pin of the converter and is connected to the drain of the internal power MOSFETs   |
| PGND             | 9,10 |     | Power ground  |

## FUNCTIONAL BLOCK DIAGRAM



## TYPICAL CHARACTERISTICS

### TABLE OF GRAPHS

|              |                                  |                  | FIGURE  |
|--------------|----------------------------------|------------------|---------|
| $\eta$       | Efficiency                       | vs Load current  | 1, 2, 3 |
| $\eta$       | Efficiency                       | vs Input voltage | 4       |
| $I_Q$        | Quiescent current                | vs Input voltage | 5, 6    |
| $f_s$        | Switching frequency              | vs Input voltage | 7       |
| $r_{DS(on)}$ | P-Channel $r_{DS(on)}$           | vs Input voltage | 8       |
| $r_{DS(on)}$ | N-Channel rectifier $r_{DS(on)}$ | vs Input voltage | 9       |
|              | Load transient response          |                  | 10      |
|              | PWM operation                    |                  | 11      |
|              | Power save mode                  |                  | 12      |
|              | Start-up                         |                  | 13      |

EFFICIENCY  
vs  
LOAD CURRENT

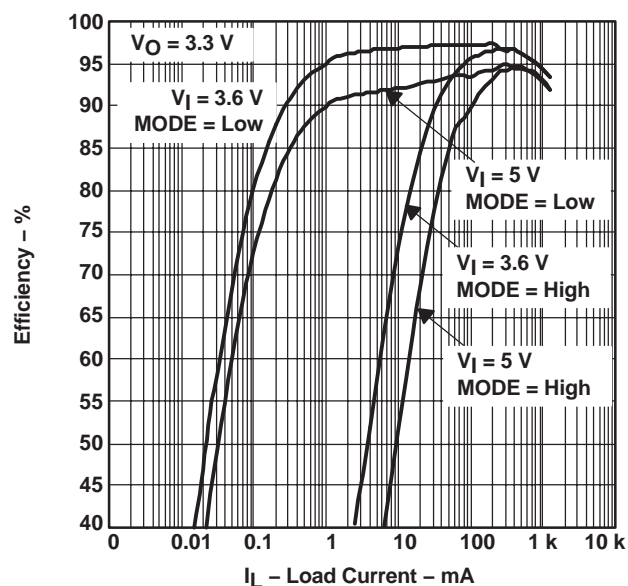


Figure 1

EFFICIENCY  
vs  
LOAD CURRENT

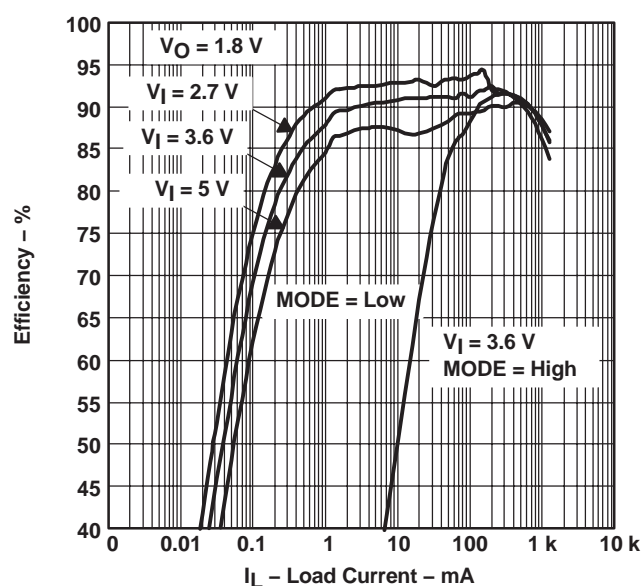


Figure 2

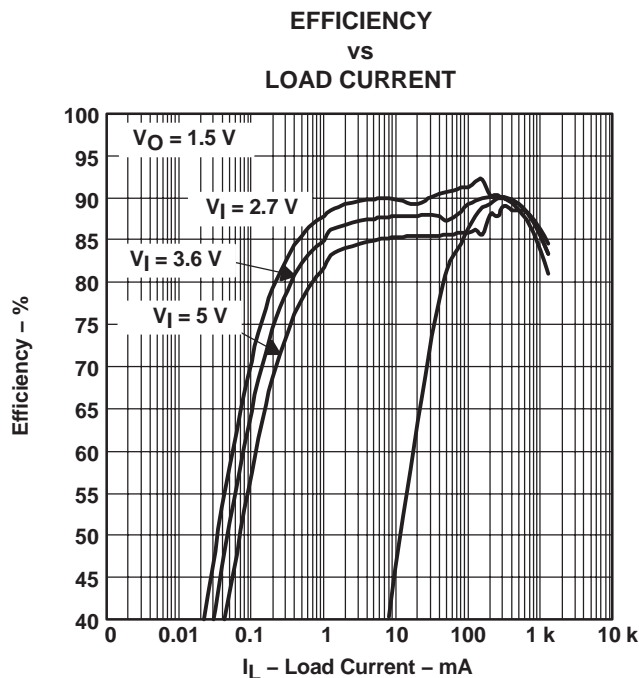


Figure 3

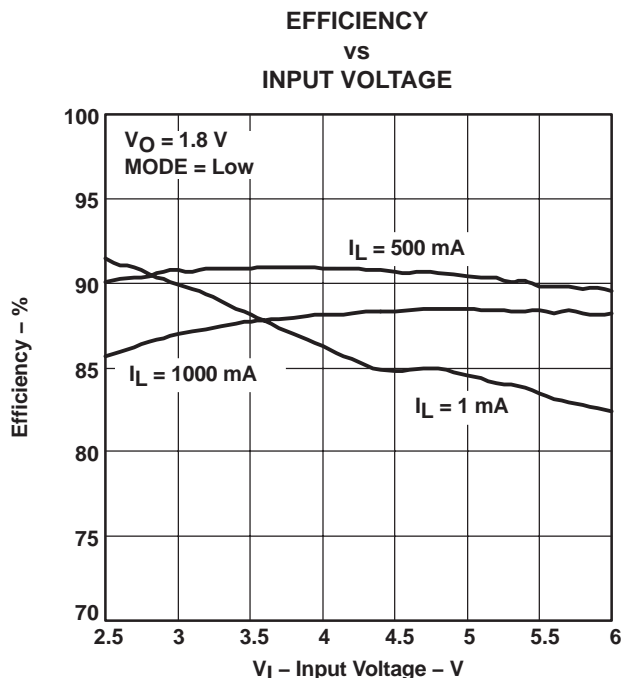


Figure 4

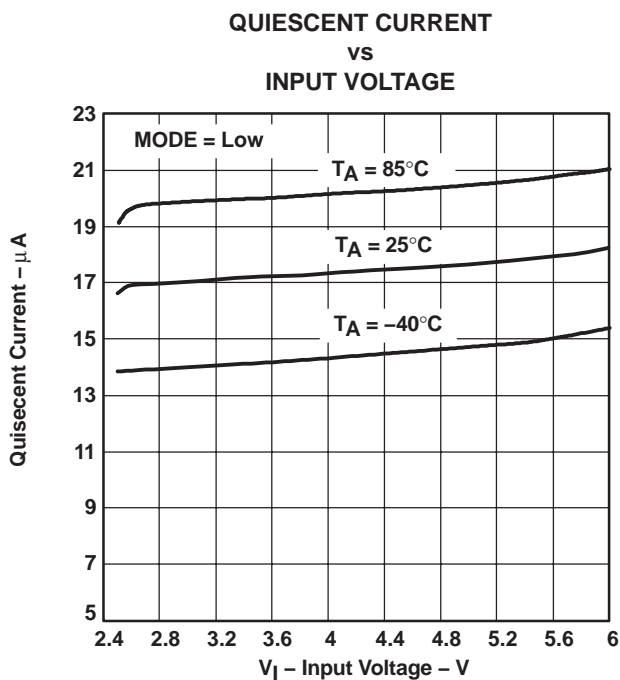


Figure 5

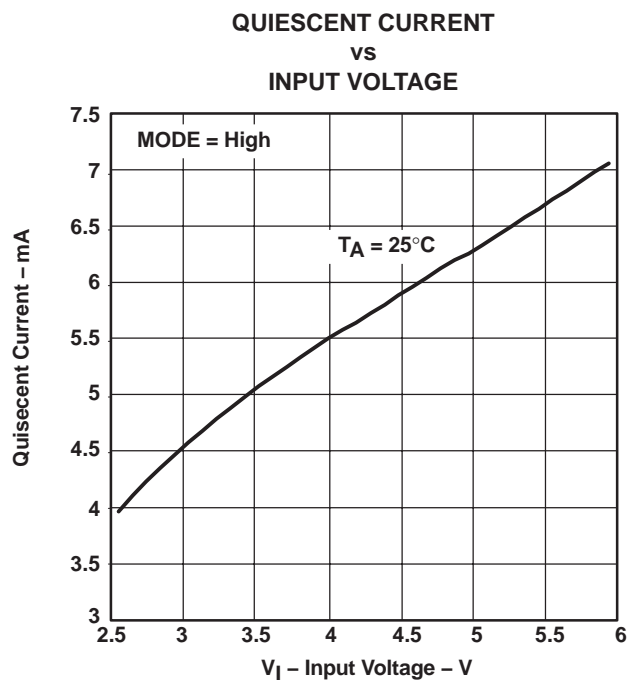


Figure 6

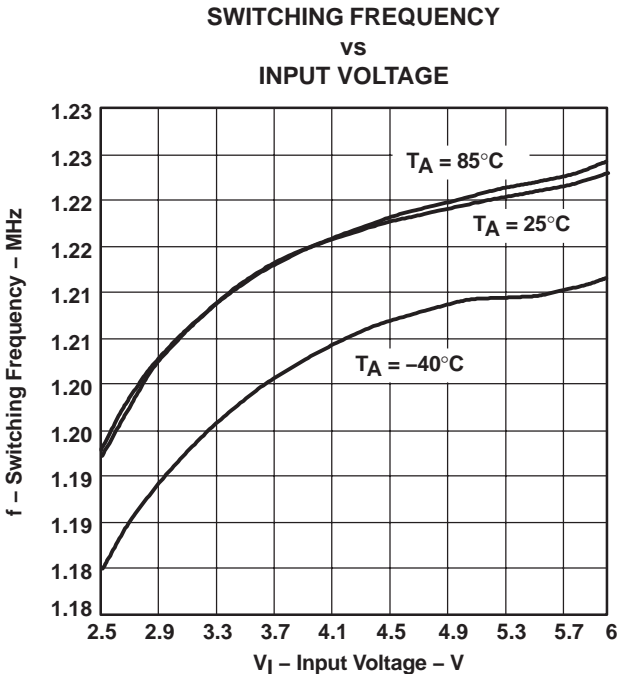


Figure 7

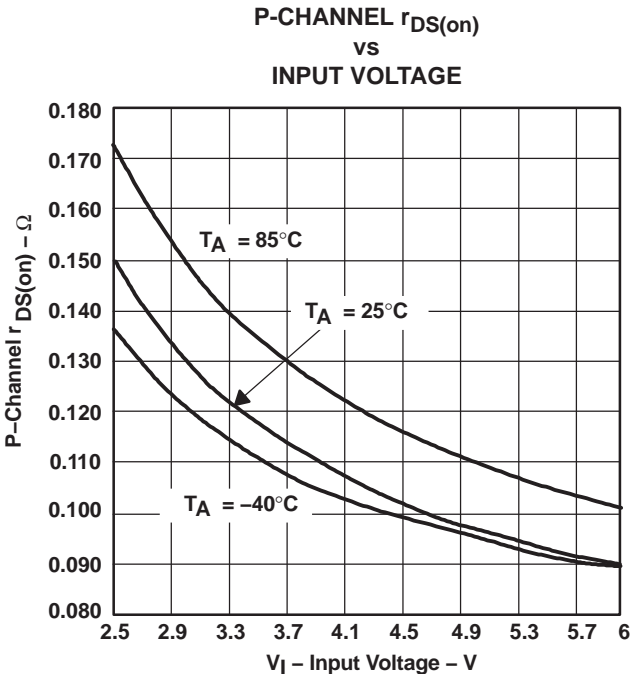


Figure 8

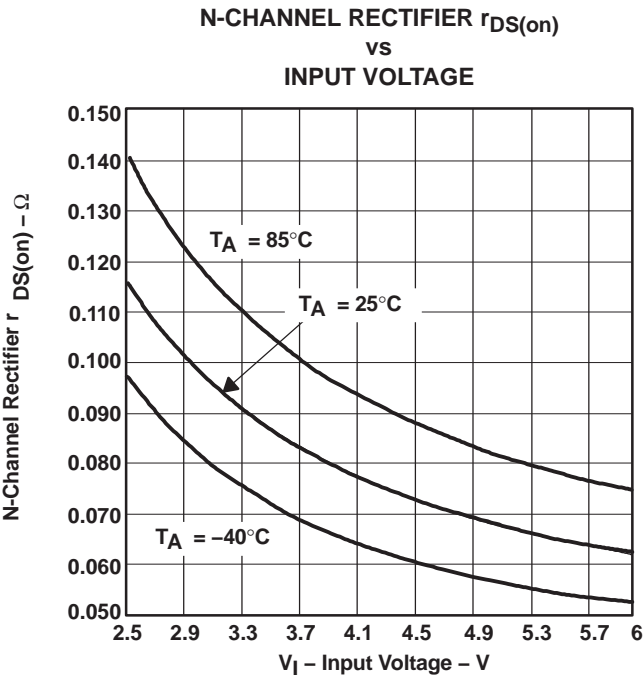


Figure 9



### LOAD TRANSIENT RESPONSE

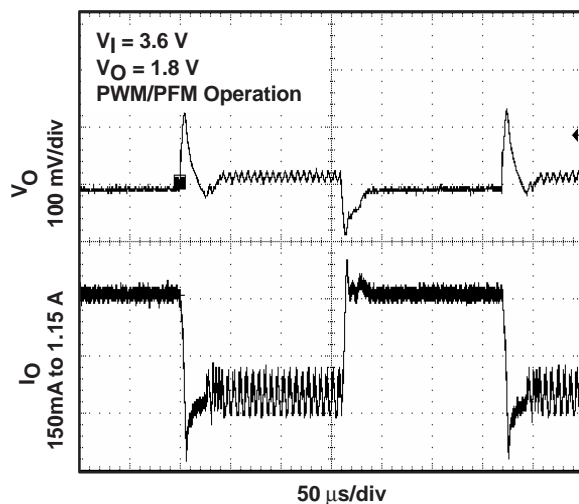


Figure 10

### PWM OPERATION

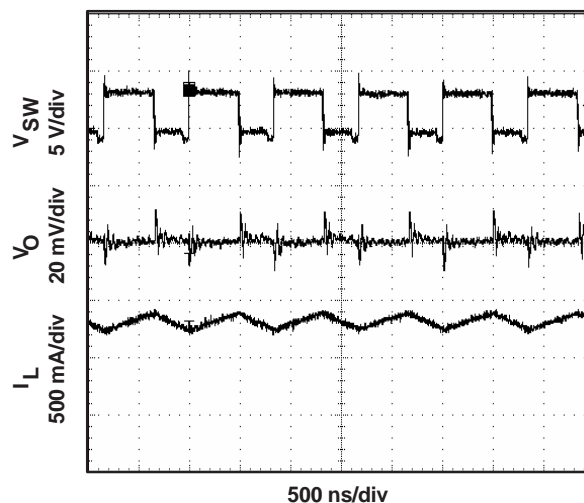


Figure 11

### POWER SAVE MODE

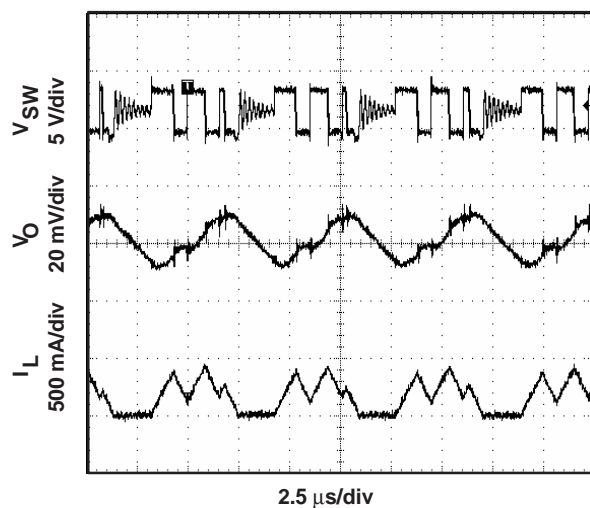


Figure 12

### START-UP

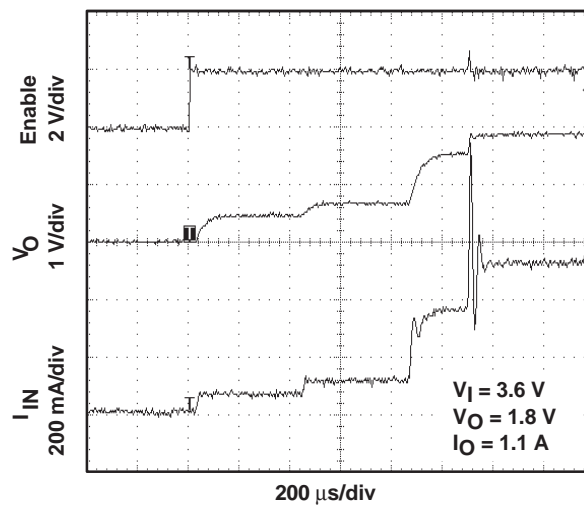


Figure 13

## DETAILED DESCRIPTION

### OPERATION

The TPS6204x is a synchronous step-down converter operating with typically 1.25 MHz fixed frequency. At moderate to heavy load currents, the device operates in pulse width modulation (PWM), and at light load currents, the device enters power save mode operation using pulse frequency modulation (PFM). When operating in PWM mode, the typical switching frequency is 1.25 MHz with a minimum switching frequency of 1 MHz. This makes the device suitable for xDSL applications minimizing RF (radio frequency) interference.

During PWM operation the converter uses a unique fast response voltage mode controller scheme with input voltage feed-forward to achieve good line and load regulation, allowing the use of small ceramic input and output capacitors. At the beginning of each clock cycle initiated by the clock signal (S) the P-channel MOSFET switch turns on and the inductor current ramps up until the comparator trips and the control logic turns off the switch. The current limit comparator also turns off the switch in case the current limit of the P-channel switch is exceeded. After the dead time preventing current shoot through, the N-channel MOSFET rectifier is turned on and the inductor current ramps down. The next cycle is initiated by the clock signal, again turning off the N-channel rectifier and turning on the P-channel switch.

The Gm amplifier as well as the input voltage determines the rise time of the saw tooth generator, and therefore, any change in input voltage or output voltage directly controls the duty cycle of the converter, giving a very good line and load transient regulation.

### POWER SAVE MODE OPERATION

As the load current decreases, the converter enters power save mode operation. During power save mode the converter operates with reduced switching frequency in PFM mode and with a minimum quiescent current maintaining high efficiency.

The converter monitors the average inductor current and the device enters power save mode when the average inductor current is below the threshold. The transition point between PWM and power save mode is given by the transition current with the following equation:

$$I_{\text{transition}} = \frac{V_I}{18.66 \, \Omega} \quad (1)$$

During power save mode the output voltage is monitored with the comparator by the threshold's comp low and comp high. As the output voltage falls below the comp low threshold set to typically 0.8% above the nominal output voltage, the P-channel switch turns on. The P-channel switch remains on until the transition current (1) is reached. Then the N-channel switch turns on completing the first cycle. The converter continues to switch with its normal duty cycle determined by the input and output voltage but with half the nominal switching frequency of 625-kHz typ. Thus the output voltage rises and as soon as the output voltage reaches the comp high threshold of 1.6%, the converter stops switching. Depending on the load current, the converter switches for a longer or shorter period of time in order to deliver the energy to the output. If the load current increases and the output voltage can not be maintained with the transition current, equation (1), the converter enters PWM again. See Figure 11 and Figure 12 under the typical graphs section and Figure 14 for power save mode operation. Among other techniques this advanced power save mode method allows high efficiency over the entire load current range and a small output ripple of typically 1% of the nominal output voltage.

Setting the power save mode thresholds to typically 0.8% and 1.6% above the nominal output voltage at light load current results in a dynamic voltage positioning achieving lower absolute voltage drops during heavy load transient changes. This allows the converter to operate with small output capacitors like 22 µF and still having a low absolute voltage drop during heavy load transient. Refer to Figure 14 as well for detailed operation of the power save mode.

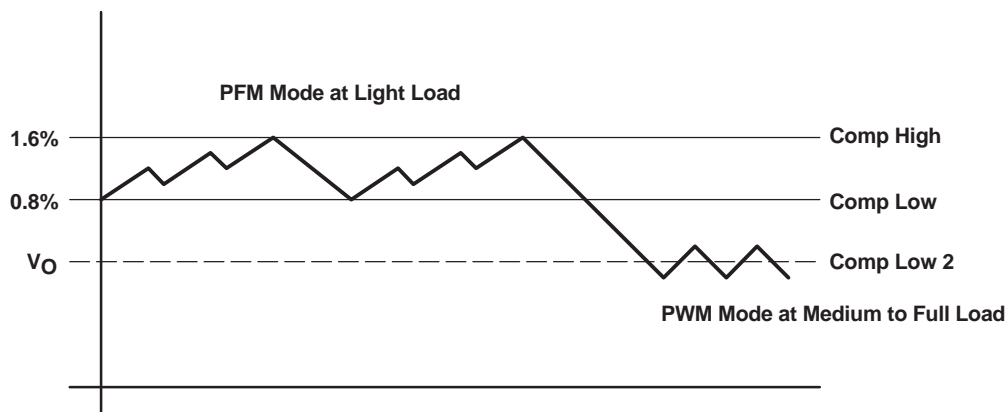


Figure 14. Power Save Mode Thresholds and Dynamic Voltage Positioning

The converter enters the fixed frequency PWM mode as soon as the output voltage falls below the comp low 2 threshold.

## DYNAMIC VOLTAGE POSITIONING

As described in the power save mode operation sections before and as detailed in Figure 14 the output voltage is typically 0.8% (i.e., 1% on average) above the nominal output voltage at light load currents, as the device is in power save mode. This gives additional headroom for the voltage drop during a load transient from light load to full load. In the other direction during a load transient from full load to light load the voltage overshoot is also minimized by turning on the N-Channel rectifier switch to pull the output voltage actively down.

## MODE (AUTOMATIC PWM/PFM OPERATION AND FORCED PWM OPERATION)

Connecting the MODE pin to GND enables the automatic PWM and power save mode operation. The converter operates in fixed frequency PWM mode at moderate to heavy loads and in the PFM mode during light loads, maintaining high efficiency over a wide load current range.

Pulling the MODE pin high forces the converter to operate constantly in the PWM mode even at light load currents. The advantage is the converter operates with a fixed switching frequency that allows simple filtering of the switching frequency for noise sensitive applications. In this mode, the efficiency is lower compared to the power save mode during light loads (see Figure 1 to Figure 3). For additional flexibility it is possible to switch from power save mode to forced PWM mode during operation. This allows efficient power management by adjusting the operation of the TPS6204x to the specific system requirements.

## 100% DUTY CYCLE LOW DROPOUT OPERATION

The TPS6204x offers a low input to output voltage difference while still maintaining regulation with the use of the 100% duty cycle mode. In this mode, the P-Channel switch is constantly turned on. This is particularly useful in battery powered applications to achieve longest operation time by taking full advantage of the whole battery voltage range. i.e. The minimum input voltage to maintain regulation depends on the load current and output voltage and can be calculated as:

$$V_{I \min} = V_{O \max} + I_{O \max} \times (r_{DS(on) \max} + R_L) \quad (2)$$

with:

$I_{O(max)}$  = maximum output current plus inductor ripple current

$r_{DS(on) \max}$  = maximum P-channel switch  $t_{DS(on)}$ .

$R_L$  = DC resistance of the inductor

$V_{O \max}$  = nominal output voltage plus maximum output voltage tolerance

## **SOFTSTART**

The TPS6204x series has an internal softstart circuit that limits the inrush current during start up. This prevents possible voltage drops of the input voltage in case a battery or a high impedance power source is connected to the input of the TPS6204x.

The softstart is implemented with a digital circuit increasing the switch current in steps of typically  $I_{LIM}/8$ ,  $I_{LIM}/4$ ,  $I_{LIM}/2$  and then the typical switch current limit 1.85 A as specified in the electrical parameter table. The start-up time mainly depends on the output capacitor and load current, see Figure 13.

## **SHORT-CIRCUIT PROTECTION**

As soon as the output voltage falls below 50% of the nominal output voltage, the converter switching frequency as well as the current limit is reduced to 50% of the nominal value. Since the short-circuit protection is enabled during start-up, the device does not deliver more than half of its nominal current limit until the output voltage exceeds 50% of the nominal output voltage. This needs to be considered in case a load acting as a current sink is connected to the output of the converter.

## **THERMAL SHUTDOWN**

As soon as the junction temperature of typically 150°C is exceeded the device goes into thermal shutdown. In this mode, the P-Channel switch and N-Channel rectifier are turned off. The device continues its operation when the junction temperature falls below typically 150°C again.

## **ENABLE**

Pulling the EN low forces the part into shutdown mode, with a shutdown current of typically 0.1  $\mu$ A. In this mode, the P-Channel switch and N-Channel rectifier are turned off and the whole device is in shut down. If an output voltage is present during shut down, which could be an external voltage source or super cap, the reverse leakage current is specified under electrical parameter table. For proper operation the enable (EN) pin must be terminated and should not be left floating.

Pulling EN high starts up the TPS6204x with the softstart as described under the section Softstart.

## **UNDERVOLTAGE LOCKOUT**

The undervoltage lockout circuit prevents device misoperation at low input voltages. It prevents the converter from turning on the switch or rectifier MOSFET with undefined conditions.

## APPLICATION INFORMATION

### ADJUSTABLE OUTPUT VOLTAGE VERSION

When the adjustable output voltage version TPS62040 is used, the output voltage is set by the external resistor divider. See Figure 15.

The output voltage is calculated as:

$$V_O = 0.5 \text{ V} \times \left(1 + \frac{R1}{R2}\right) \quad (3)$$

with  $R1 + R2 \leq 1 \text{ M}\Omega$  and internal reference voltage  $V_{ref}$  typical = 0.5 V

$R1 + R2$  should not be greater than 1 M $\Omega$  because of stability reasons. To keep the operating quiescent current to a minimum, the feedback resistor divider should have high impedance with  $R1+R2 \leq 1 \text{ M}\Omega$ . Due to this and the low reference voltage of  $V_{ref} = 0.5 \text{ V}$ , the noise on the feedback pin (FB) needs to be minimized. Using a capacitive divider C1 and C2 across the feedback resistors minimizes the noise at the feedback, without degrading the line or load transient performance.

C1 and C2 should be selected as:

$$C1 = \frac{1}{2 \times \pi \times 10 \text{ kHz} \times R1} \quad (4)$$

with:

$R1$  = upper resistor of voltage divider

$C1$  = upper capacitor of voltage divider

For  $C1$  a value should be chosen that comes closest to the calculated result.

$$C2 = \frac{R1}{R2} \times C1 \quad (5)$$

with:

$R2$  = lower resistor of voltage divider

$C2$  = lower capacitor of voltage divider

For  $C2$ , the selected capacitor value should always be selected larger than the calculated result. For example, in Figure 15 for  $C2$  100 pF are selected for a calculated result of  $C2 = 88.42 \text{ pF}$ .

If quiescent current is not a key design parameter  $C1$  and  $C2$  can be omitted, and a low impedance feedback divider has to be used with  $R1 + R2 < 100 \text{ k}\Omega$ . This reduces the noise available on the feedback pin (FB) as well but increases the overall quiescent current during operation. The higher the programmed output voltage the lower the feedback impedance has to be for best operation when not using  $C1$  and  $C2$ .

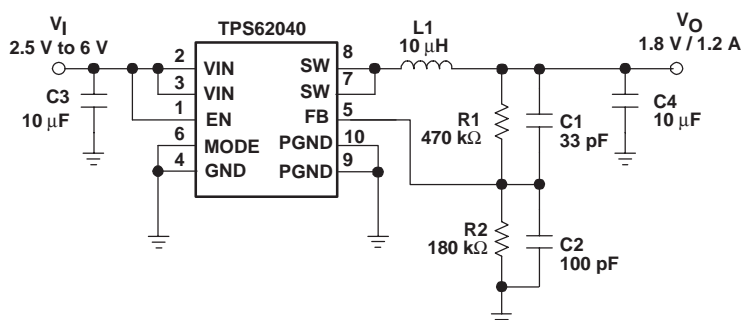


Figure 15. Adjustable Output Voltage Version

## Inductor Selection

The TPS6204x typically uses a 6.2-μH output inductor. Larger or smaller inductor values can be used to optimize the performance of the device for specific operation conditions. The selected inductor has to be rated for its dc resistance and saturation current. The dc resistance of the inductance directly influences the efficiency of the converter. Therefore an inductor with the lowest dc resistance should be selected for highest efficiency.

Formula (7) calculates the maximum inductor current under static load conditions. The saturation current of the inductor should be rated higher than the maximum inductor current as calculated with formula (7). This is needed because during heavy load transient the inductor current rises above the value calculated under (7).

$$\Delta I_L = V_O \times \frac{1 - \frac{V_O}{V_I}}{L \times f} \quad (6)$$

$$I_{L \max} = I_{O \max} + \frac{\Delta I_L}{2} \quad (7)$$

with

$f$  = Switching frequency (1.25 MHz typical)

$L$  = Inductor value

$\Delta I_L$  = Peak-to-peak inductor ripple current

$I_{L \max}$  = Maximum inductor current

The highest inductor current occurs at maximum  $V_I$ .

Open core inductors have a soft saturation characteristic and they can usually handle higher inductor currents versus a comparable shielded inductor. A more conservative approach is to select the inductor current rating just for the maximum switch current of 2.2 A for the TPS6204x. Keep in mind that the core material from inductor to inductor differs and has an impact on the efficiency, especially at high switching frequencies. Refer to Table 1 and the typical applications and inductors selection.

**Table 1. Inductor Selection**

| INDUCTOR VALUE | DIMENSIONS               | COMPONENT SUPPLIER   |
|----------------|--------------------------|----------------------|
| 4.7 μH         | 5,0 mm × 5,0 mm × 3,0 mm | Sumida CDRH4D28C-4.7 |
| 4.7 μH         | 5,2 mm × 5,2 mm × 2,5 mm | Coiltronics SD25-4R7 |
| 5.3 μH         | 5,7 mm × 5,7 mm × 3,0 mm | Sumida CDRH5D28-5R3  |
| 6.2 μH         | 5,7 mm × 5,7 mm × 3,0 mm | Sumida CDRH5D28-6R2  |
| 6.0 μH         | 7,0 mm × 7,0 mm × 3,0 mm | Sumida CDRH6D28-6R0  |

## Output Capacitor Selection

The advanced fast response voltage mode control scheme of the TPS6204x allows the use of small ceramic capacitors with a typical value of 22  $\mu\text{F}$  without having large output voltage under and overshoots during heavy load transients. Ceramic capacitors having low ESR values have the lowest output voltage ripple and are recommended. If required, tantalum capacitors may also be used. Refer to Table 2 for component selection.

If ceramic output capacitor are used, the capacitor RMS ripple current rating always meets the application requirements. Just for completeness the RMS ripple current is calculated as:

$$I_{\text{RMS Cout}} = V_O \times \frac{1 - \frac{V_O}{V_I}}{L \times f} \times \frac{1}{2 \times \sqrt{3}} \quad (8)$$

At nominal load current the device operates in PWM mode and the overall output voltage ripple is the sum of the voltage spike caused by the output capacitor ESR plus the voltage ripple caused by charging and discharging the output capacitor:

$$\Delta V_O = V_O \times \frac{1 - \frac{V_O}{V_I}}{L \times f} \times \left( \frac{1}{8 \times C_O \times f} + \text{ESR} \right) \quad (9)$$

Where the highest output voltage ripple occurs at the highest input voltage,  $V_I$ .

At light load currents, the device operates in power save mode and the output voltage ripple is independent of the output capacitor value. The output voltage ripple is set by the internal comparator thresholds. The typical output voltage ripple is 1% of the nominal output voltage.

## Input Capacitor Selection

Because of the nature of the buck converter having a pulsating input current, a low ESR input capacitor is required for best input voltage filtering and minimizing the interference with other circuits caused by high input voltage spikes. The input capacitor should have a minimum value of 22  $\mu\text{F}$ . The input capacitor can be increased without any limit for better input voltage filtering.

**Table 2. Input and Output Capacitor Selection**

| CAPACITOR<br>VALUE | CASE SIZE | COMPONENT SUPPLIER        | COMMENTS |
|--------------------|-----------|---------------------------|----------|
| 22 $\mu\text{F}$   | 1206      | Taiyo Yuden JMK316BJ226ML | Ceramic  |
| 22 $\mu\text{F}$   | 1210      | Taiyo Yuden JMK325BJ226MM | Ceramic  |

## Layout Considerations

For all switching power supplies, the layout is an important step in the design especially at high peak currents and switching frequencies. If the layout is not carefully done, the regulator might show stability problems as well as EMI problems. Therefore, use wide and short traces for the main current paths as indicated in bold in Figure 16. These traces should be routed first. The input capacitor should be placed as close as possible to the IC pins as well as the inductor and output capacitor. The feedback resistor network should be routed away from the inductor and switch node to minimize noise and magnetic interference. To further minimize noise from coupling into the feedback network and feedback pin, the ground plane or ground traces should be used for shielding. A common ground plane or a star ground as shown below should be used. This becomes very important especially at high switching frequencies of 1.25 MHz.

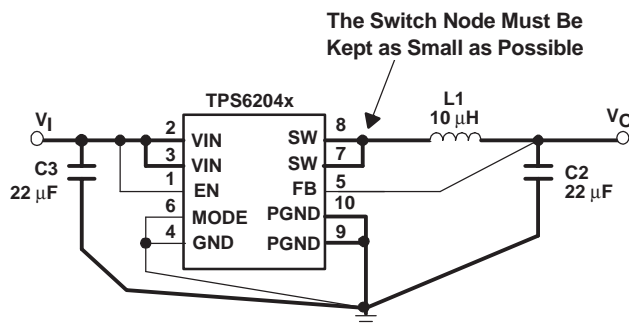


Figure 16. Layout Diagram

## THERMAL INFORMATION

One of the most influential components on the thermal performance of a package is board design. In order to take full advantage of the heat dissipating abilities of the PowerPAD™ packages, a board should be used that acts similar to a heat sink and allows for the use of the exposed (and solderable), deep downset pad. For further information please refer to Texas Instruments application note (SLMA002) *PowerPAD Thermally Enhanced Package*.

The PowerPAD™ of the 10-pin MSOP package has an area of 1,52 mm × 1,79 mm (± 0,05 mm) and must be soldered to the PCB to lower the thermal resistance. Thermal vias to the next layer further reduce the thermal resistance.



## TYPICAL APPLICATIONS

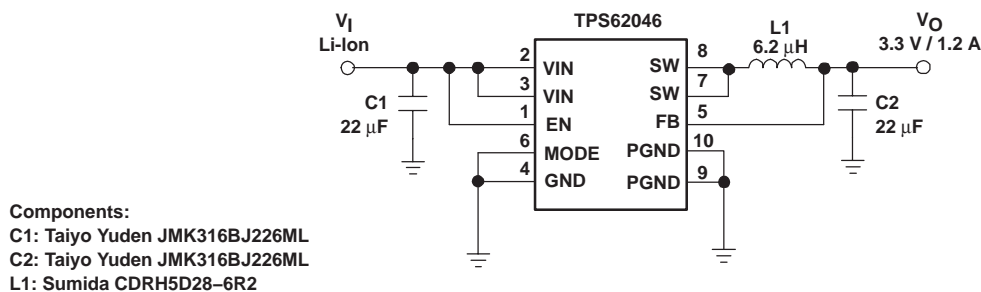


Figure 17. Li-Ion to 3.3 V/1.2 A Conversion

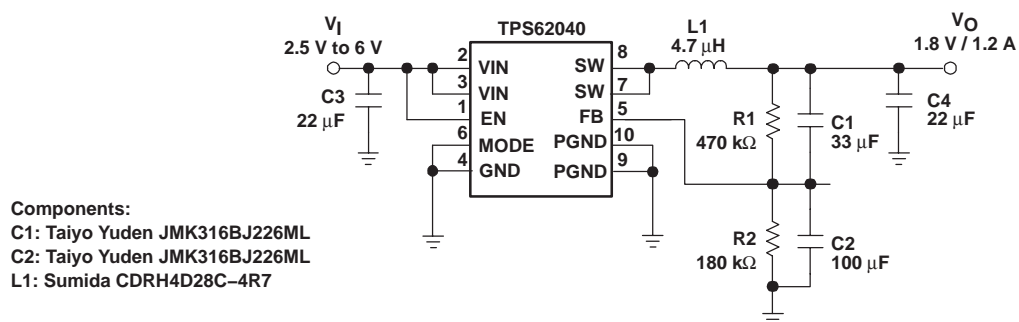
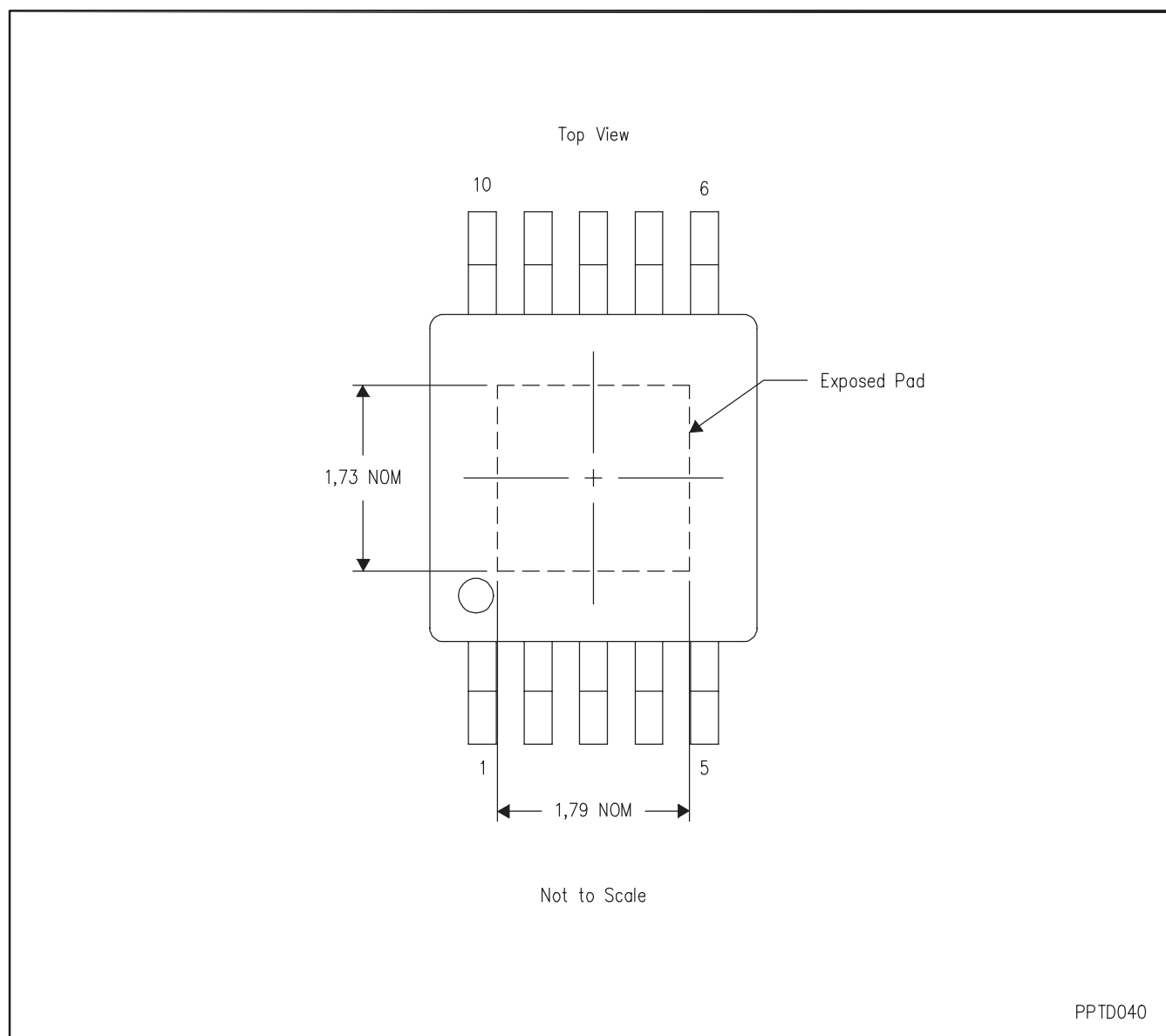


Figure 18. Li-Ion to 1.8 V/1.2 A Conversion Using the Adjustable Output Voltage Version

## THERMAL PAD MECHANICAL DATA

DGQ (S-PDSO-G10)

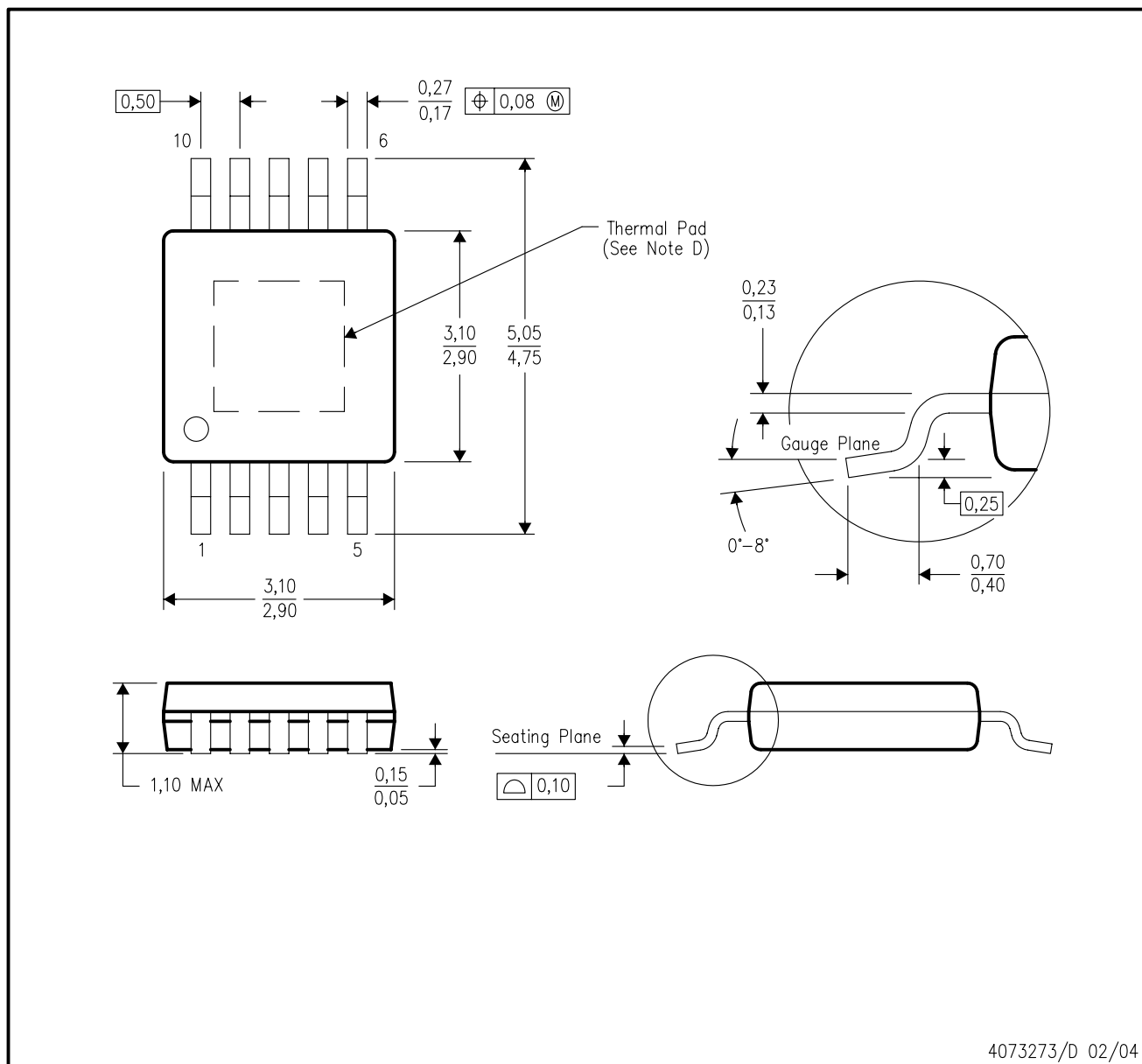
PowerPAD™ PLASTIC SMALL-OUTLINE



- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - For additional information on the PowerPAD™ package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, **PowerPAD Thermally Enhanced Package**, Texas Instruments Literature No. SLMA002 and Application Brief, **PowerPAD Made Easy**, Texas Instruments Literature No. SLMA004. Both documents are available at [www.ti.com](http://www.ti.com).

DGQ (S-PDSO-G10)

PowerPAD™ PLASTIC SMALL-OUTLINE PACKAGE



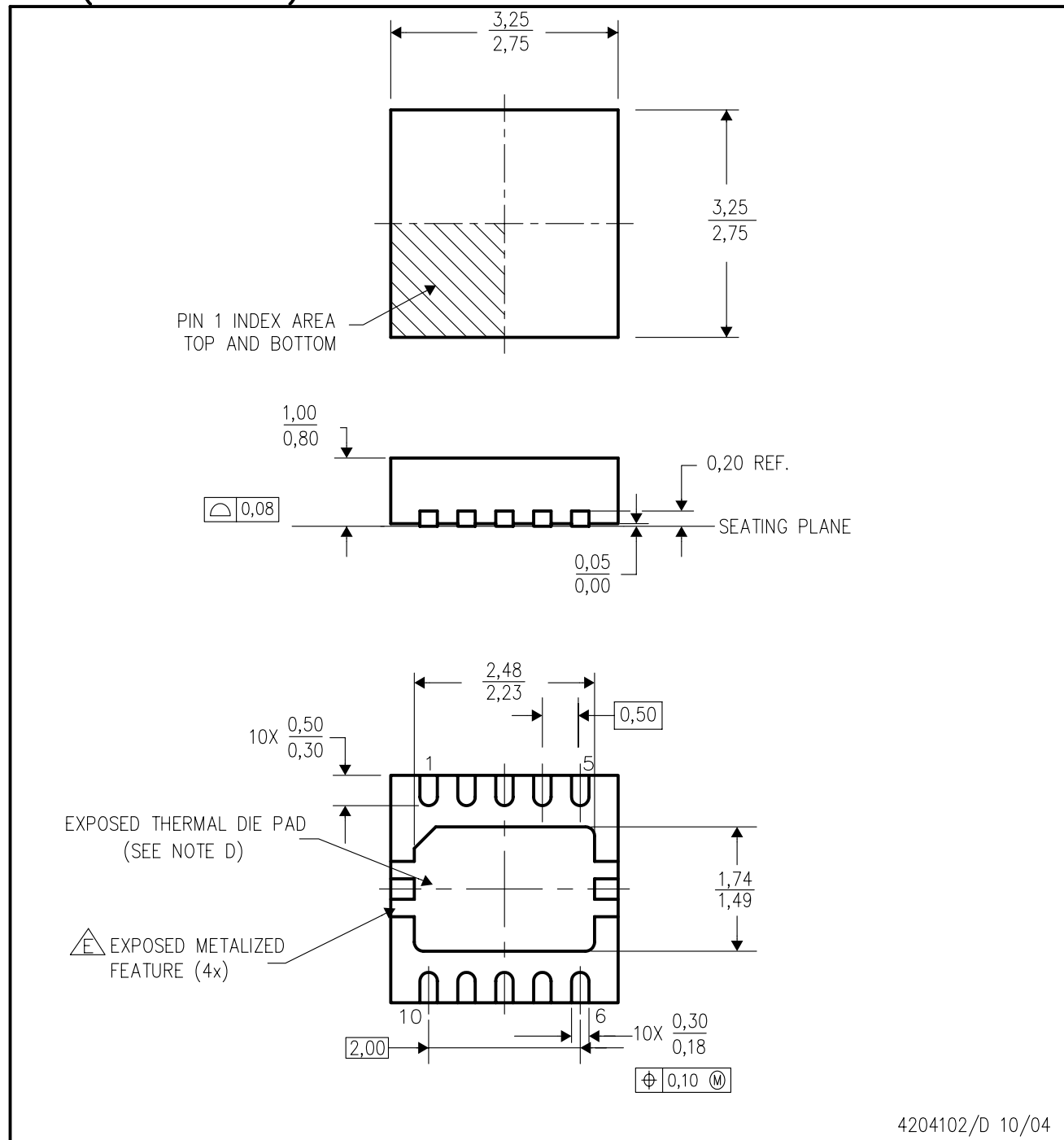
- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - Body dimensions do not include mold flash or protrusion.
  - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
  - Falls within JEDEC MO-187 variation BA-T.

PowerPAD is a trademark of Texas Instruments.

DRC (S-PDSO-N10)

CUSTOM DEVICE

PLASTIC SMALL OUTLINE



## NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Small Outline No-Lead (SON) package configuration.
- D. The package thermal performance may be enhanced by bonding the thermal die pad to an external thermal plane.
- E. Metalized features are supplier options and may not be on the package.

## IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

| <b>Products</b>  |  | <b>Applications</b> |  |
|------------------|--|---------------------|--|
| Amplifiers       | <a href="http://amplifier.ti.com">amplifier.ti.com</a>             | Audio               | <a href="http://www.ti.com/audio">www.ti.com/audio</a>                   |
| Data Converters  | <a href="http://dataconverter.ti.com">dataconverter.ti.com</a>     | Automotive          | <a href="http://www.ti.com/automotive">www.ti.com/automotive</a>         |
| DSP              | <a href="http://dsp.ti.com">dsp.ti.com</a>                         | Broadband           | <a href="http://www.ti.com/broadband">www.ti.com/broadband</a>           |
| Interface        | <a href="http://interface.ti.com">interface.ti.com</a>             | Digital Control     | <a href="http://www.ti.com/digitalcontrol">www.ti.com/digitalcontrol</a> |
| Logic            | <a href="http://logic.ti.com">logic.ti.com</a>                     | Military            | <a href="http://www.ti.com/military">www.ti.com/military</a>             |
| Power Mgmt       | <a href="http://power.ti.com">power.ti.com</a>                     | Optical Networking  | <a href="http://www.ti.com/opticalnetwork">www.ti.com/opticalnetwork</a> |
| Microcontrollers | <a href="http://microcontroller.ti.com">microcontroller.ti.com</a> | Security            | <a href="http://www.ti.com/security">www.ti.com/security</a>             |
|                  |  | Telephony           | <a href="http://www.ti.com/telephony">www.ti.com/telephony</a>           |
|                  |  | Video & Imaging     | <a href="http://www.ti.com/video">www.ti.com/video</a>                   |
|                  |  | Wireless            | <a href="http://www.ti.com/wireless">www.ti.com/wireless</a>             |

Mailing Address: Texas Instruments  
Post Office Box 655303 Dallas, Texas 75265

Copyright © 2004, Texas Instruments Incorporated

Copyright © Each Manufacturing Company.

All Datasheets cannot be modified without permission.

This datasheet has been download from :

[www.AllDataSheet.com](http://www.AllDataSheet.com)

100% Free DataSheet Search Site.

Free Download.

No Register.

Fast Search System.

[www.AllDataSheet.com](http://www.AllDataSheet.com)