

INTEGRATED CIRCUITS

DATA SHEET

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- The IC04 LOCMOS HE4000B Logic Family Specifications HEF, HEC
- The IC04 LOCMOS HE4000B Logic Package Outlines/Information HEF, HEC

HEF4067B MSI 16-channel analogue multiplexer/demultiplexer

Product specification
File under Integrated Circuits, IC04

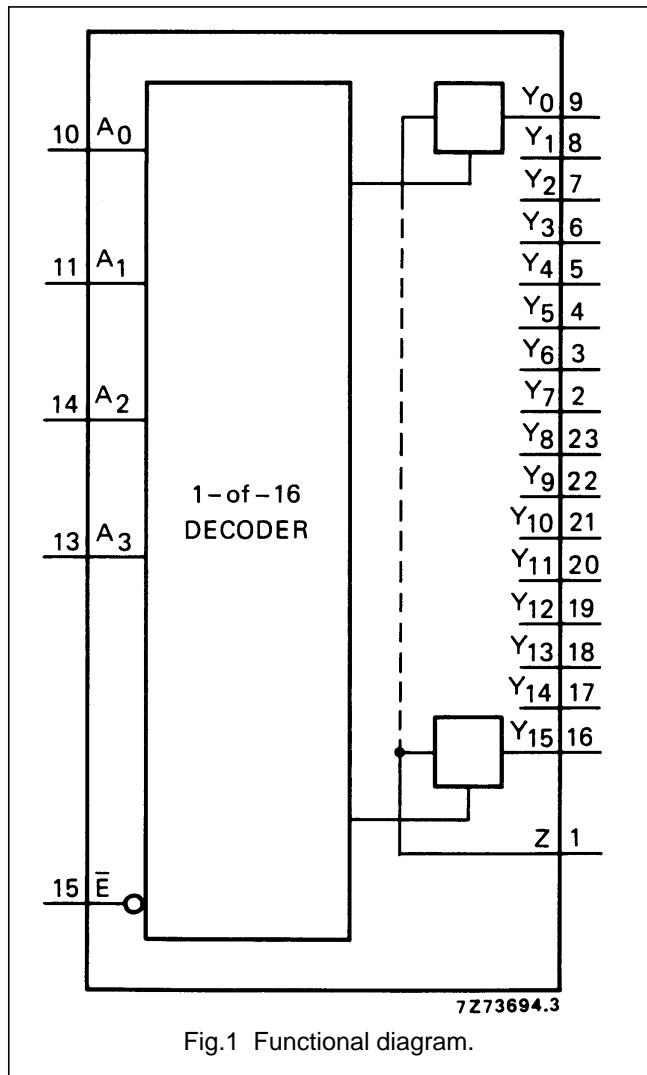
January 1995

16-channel analogue multiplexer/demultiplexer

HEF4067B
MSI

DESCRIPTION

The HEF4067B is a 16-channel analogue multiplexer/demultiplexer with four address inputs (A_0 to A_3), an active LOW enable input (\bar{E}), sixteen independent inputs/outputs (Y_0 to Y_{15}) and a common input/output (Z).



The device contains sixteen bidirectional analogue switches, each with one side connected to an independent input/output (Y_0 to Y_{15}) and the other side connected to the common input/output (Z).

With \bar{E} LOW, one of the sixteen switches is selected (low impedance ON-state) by A_0 to A_3 . All unselected switches are in the high impedance OFF-state. With \bar{E} HIGH all switches are in the high impedance OFF-state, independent of A_0 to A_3 .

The analogue inputs/outputs (Y_0 to Y_{15} and Z) can swing between V_{DD} as a positive limit and V_{SS} as a negative limit. V_{DD} to V_{SS} may not exceed 15 V.

FAMILY DATA, I_{DD} LIMITS category MSI

See Family Specifications

HEF4067BP(N): 24-lead DIL; plastic
(SOT101-1)

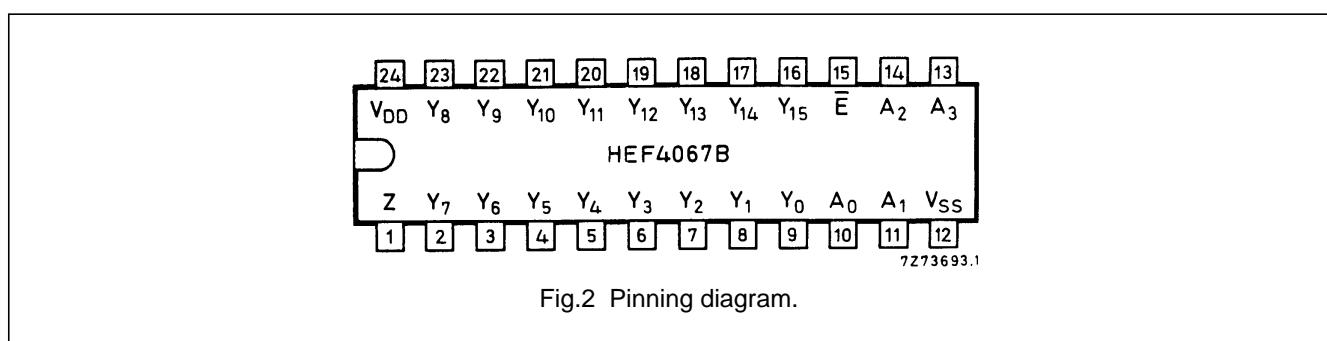
HEF4067BD(F): 24-lead DIL; ceramic (cerdip)
(SOT94)

HEF4067BT(D): 24-lead SO; plastic
(SOT137-1)

(): Package Designator North America

PINNING

Y_0 to Y_{15}	independent inputs/outputs
A_0 to A_3	address inputs
\bar{E}	enable input (active LOW)
Z	common input/output



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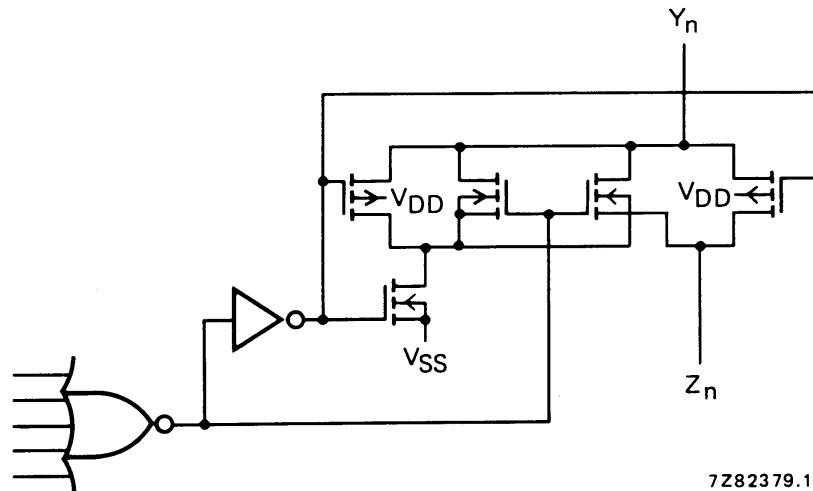


Fig.3 Schematic diagram (one switch).

FUNCTION TABLE

INPUTS					CHANNEL
\bar{E}	A_3	A_2	A_1	A_0	ON
L	L	L	L	L	$Y_0 - Z$
L	L	L	L	H	$Y_1 - Z$
L	L	L	H	L	$Y_2 - Z$
L	L	L	H	H	$Y_3 - Z$
L	L	H	L	L	$Y_4 - Z$
L	L	H	L	H	$Y_5 - Z$
L	L	H	H	L	$Y_6 - Z$
L	L	H	H	H	$Y_7 - Z$
L	H	L	L	L	$Y_8 - Z$
L	H	L	L	H	$Y_9 - Z$
L	H	L	H	L	$Y_{10} - Z$
L	H	L	H	H	$Y_{11} - Z$
L	H	H	L	L	$Y_{12} - Z$
L	H	H	L	H	$Y_{13} - Z$
L	H	H	H	L	$Y_{14} - Z$
L	H	H	H	H	$Y_{15} - Z$
H	X	X	X	X	none

Note

1. H = HIGH state (the more positive voltage)
L = LOW state (the less positive voltage)
X = state is immaterial

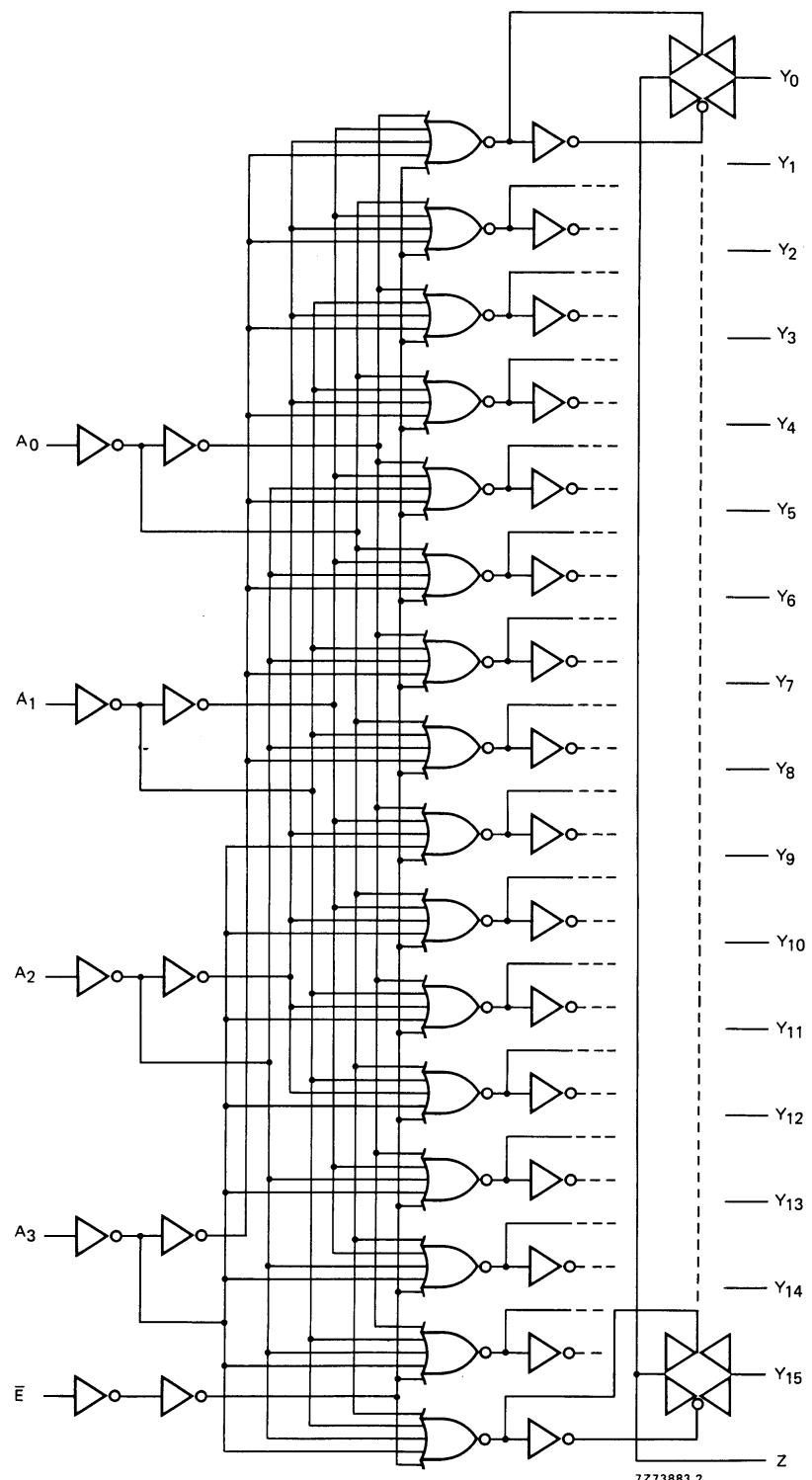
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Fig.4 Logic diagram.

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DC CHARACTERISTICS

$T_{amb} = 25^\circ\text{C}$

	V_{DD} V	SYMBOL	TYP.	MAX.	CONDITIONS
ON resistance	5	R_{ON}	350	2500	Ω
	10		80	245	Ω
	15		60	175	Ω
ON resistance	5	R_{ON}	115	340	Ω
	10		50	160	Ω
	15		40	115	Ω
ON resistance	5	R_{ON}	120	365	Ω
	10		65	200	Ω
	15		50	155	Ω
'Δ' ON resistance between any two channels	5	ΔR_{ON}	25	—	Ω
	10		10	—	Ω
	15		5	—	Ω
OFF-state leakage current, all channels OFF	5	I_{OZZ}	—	—	nA
	10		—	—	nA
	15		—	1000	nA
OFF-state leakage current, any channel	5	I_{OZY}	—	—	nA
	10		—	—	nA
	15		—	200	nA

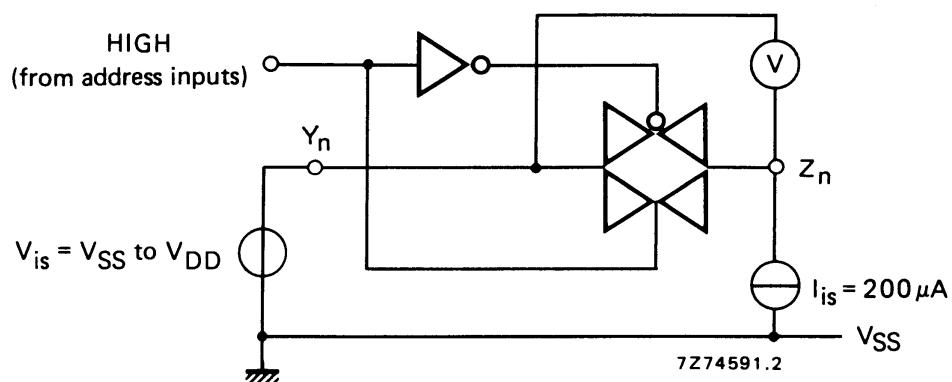
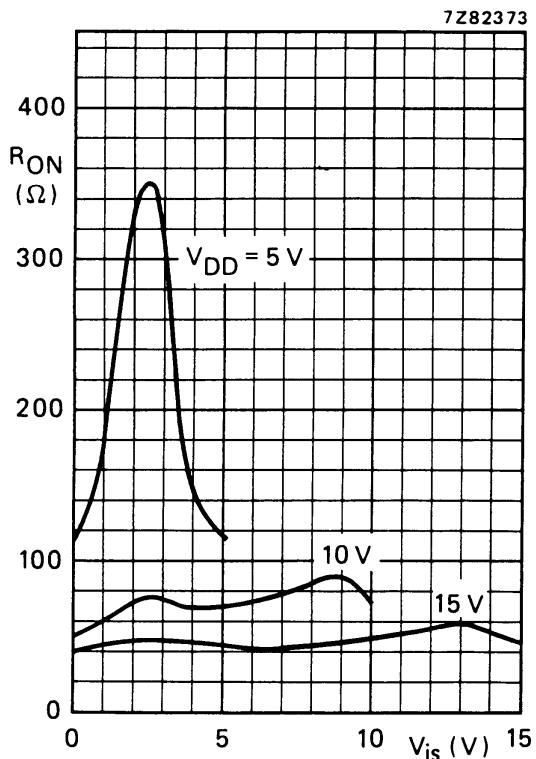


Fig.5 Test set-up for measuring R_{ON} .

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$I_{DS} = 200 \mu A$
 $V_{SS} = 0 V$

Fig.6 Typical $R_{DS(on)}$ as a function of input voltage.

NOTE

To avoid drawing V_{DD} current out of terminal Z, when switch current flows into terminals Y, the voltage drop across the bidirectional switch must not exceed 0,4 V. If the switch current flows into terminal Z, no V_{DD} current will flow out of terminals Y, in this case there is no limit for the voltage drop across the switch, but the voltages at Y and Z may not exceed V_{DD} or V_{SS} .

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AC CHARACTERISTICS

$V_{SS} = 0 \text{ V}$; $T_{amb} = 25 \text{ }^{\circ}\text{C}$; input transition times $\leq 20 \text{ ns}$

	V_{DD} V	TYPICAL FORMULA FOR P (μW)	
Dynamic power dissipation per package (P)	5 10 15	$1\ 100 f_i + \sum (f_o C_L) \times V_{DD}^2$ $5\ 000 f_i + \sum (f_o C_L) \times V_{DD}^2$ $13\ 300 f_i + \sum (f_o C_L) \times V_{DD}^2$	where f_i = input freq. (MHz) f_o = output freq. (MHz) C_L = load capacitance (pF) $\sum (f_o C_L)$ = sum of outputs V_{DD} = supply voltage (V)

AC CHARACTERISTICS ^{(1), (2)}

$V_{SS} = 0 \text{ V}$; $T_{amb} = 25 \text{ }^{\circ}\text{C}$; input transition times $\leq 20 \text{ ns}$

	V_{DD} V	SYMBOL	TYP.	MAX.	
Propagation delays $V_{is} \rightarrow V_{os}$ HIGH to LOW	5	t_{PHL}	30	60	ns
	10		15	25	ns
	15		10	20	ns
	5	t_{PLH}	25	50	ns
	10		10	20	ns
	15		10	20	ns
	5	t_{PHL}	190	380	ns
	10		70	145	ns
	15		50	100	ns
	5	t_{PLH}	175	345	ns
	10		70	140	ns
	15		50	100	ns
Output disable times $\bar{E} \rightarrow V_{os}$ HIGH	5	t_{PHZ}	195	385	ns
	10		140	280	ns
	15		130	260	ns
	5	t_{PLZ}	215	435	ns
	10		180	355	ns
	15		170	340	ns
	5	t_{PZH}	155	315	ns
	10		70	135	ns
	15		50	100	ns
Output enable times $\bar{E} \rightarrow V_{os}$ LOW	5	t_{PZL}	170	340	ns
	10		70	140	ns
	15		50	100	ns
	5	t_{PZL}	155	315	ns
	10		70	135	ns
	15		50	100	ns

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AC CHARACTERISTICS

$V_{SS} = 0 \text{ V}$; $T_{amb} = 25^\circ\text{C}$; input transition times $\leq 20 \text{ ns}$

	V_{DD} V	SYMBOL	TYP.	MAX.	
Distortion, sine-wave response	5		0,25	%	note 6
	10		0,04	%	
	15		0,04	%	
Crosstalk between any two channels	5		–	MHz	note 7
	10		1	MHz	
	15		–	MHz	
Crosstalk; enable or address input to output	5		–	mV	note 8
	10		50	mV	
	15		–	mV	
OFF-state feed-through	5		–	MHz	note 9
	10		1	MHz	
	15		–	MHz	
ON-state frequency response	5		13	MHz	note 10
	10		40	MHz	
	15		70	MHz	

Notes

1. V_{is} is the input voltage at a Y or Z terminal, whichever is assigned as input.
2. V_{os} is the output voltage at a Y or Z terminal, whichever is assigned as output.
3. $R_L = 10 \text{ k}\Omega$ to V_{SS} ; $C_L = 50 \text{ pF}$ to V_{SS} ; $\bar{E} = V_{SS}$; $V_{is} = V_{DD}$ (square-wave); see Fig.7.
4. $R_L = 10 \text{ k}\Omega$; $C_L = 50 \text{ pF}$ to V_{SS} ; $\bar{E} = V_{SS}$; $A_n = V_{DD}$ (square-wave); $V_{is} = V_{DD}$ and R_L to V_{SS} for t_{PLH} ; $V_{is} = V_{SS}$ and R_L to V_{DD} for t_{PHL} ; see Fig.7.
5. $R_L = 10 \text{ k}\Omega$; $C_L = 50 \text{ pF}$ to V_{SS} ; $\bar{E} = V_{DD}$ (square-wave); $V_{is} = V_{DD}$ and R_L to V_{SS} for t_{PZH} and t_{PZL} ; $V_{is} = V_{SS}$ and R_L to V_{DD} for t_{PLZ} and t_{PZL} ; see Fig.7.
6. $R_L = 10 \text{ k}\Omega$; $C_L = 15 \text{ pF}$; channel ON; $V_{is} = \frac{1}{2} V_{DD(p-p)}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$); $f_{is} = 1 \text{ kHz}$; see Fig.8.
7. $R_L = 1 \text{ k}\Omega$; $V_{is} = \frac{1}{2} V_{DD(p-p)}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$);

$$20 \log \frac{V_{os}}{V_{is}} = -50 \text{ dB}; \text{ see Fig.9.}$$

8. $R_L = 10 \text{ k}\Omega$ to V_{SS} ; $C_L = 15 \text{ pF}$ to V_{SS} ; \bar{E} or $A_n = V_{DD}$ (square-wave); crosstalk is $|V_{os}|$ (peak value); see Fig.7.

9. $R_L = 1 \text{ k}\Omega$; $C_L = 5 \text{ pF}$; channel OFF; $V_{is} = \frac{1}{2} V_{DD(p-p)}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$);

$$20 \log \frac{V_{os}}{V_{is}} = -50 \text{ dB}; \text{ see Fig.8.}$$

10. $R_L = 1 \text{ k}\Omega$; $C_L = 5 \text{ pF}$; channel ON; $V_{is} = \frac{1}{2} V_{DD(p-p)}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$);

$$20 \log \frac{V_{os}}{V_{is}} = -3 \text{ dB}; \text{ see Fig.8.}$$

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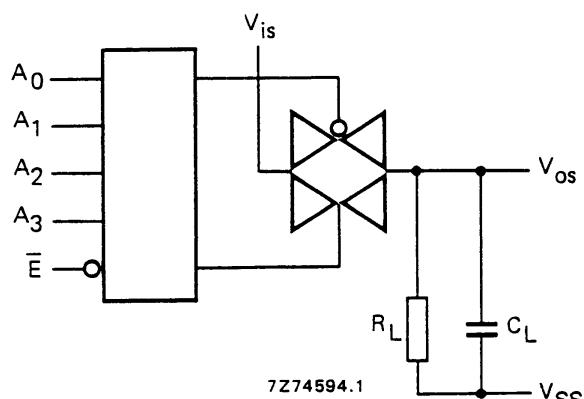


Fig.7

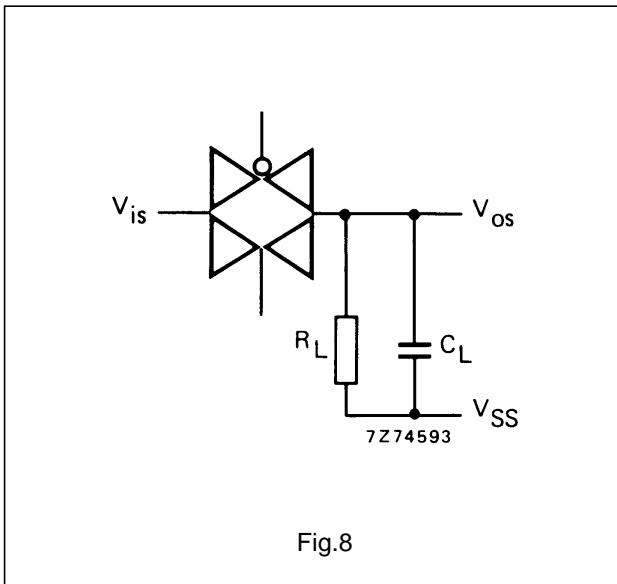


Fig.8

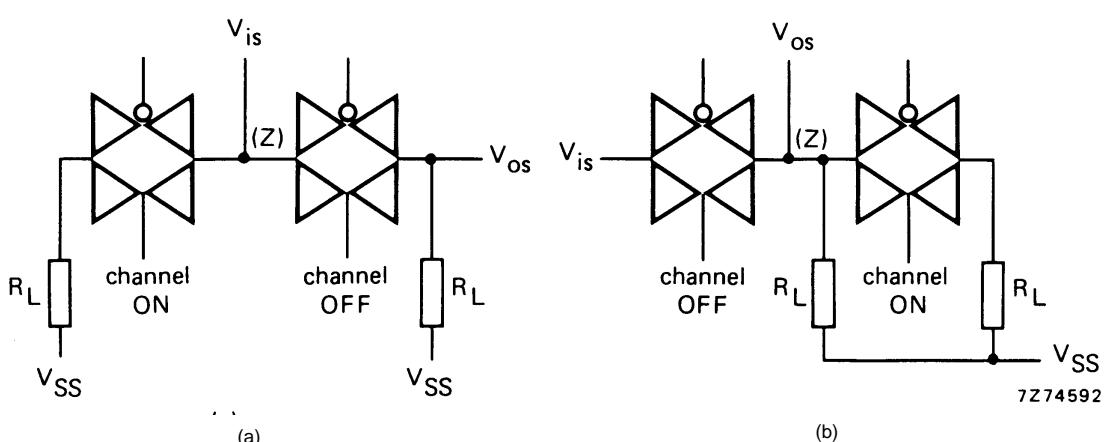


Fig.9

APPLICATION INFORMATION

Some examples of applications for the HEF4067B are:

- Analogue multiplexing and demultiplexing.
- Digital multiplexing and demultiplexing.
- Signal gating.

NOTE

If break before make is needed, then it is necessary to use the enable input.